

Optimizing a Camera ISP to Automatically Improve Computer Vision Accuracy

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Agenda

01

02

Challenges Camera ISP Tuning



04

Demo Atlas Cloud-Enabled Workflow

Atlas

Optimizing ISPs for Computer Vision at Scale **Automotive Case Study**

Optimizing a Front-facing Camera for Computer Vision





Challenges with Camera ISP Tuning Today



Typical Camera System



Massive parameter space controls the image quality for each camera configuration





Challenges With Manual ISP Tuning





Resource-Intensive

"Too much cost & time"



Limited

"Manual tuning does **NOT** work for computer vision"



Inefficient

"It doesn't scale to my projects"



Uncertain

"Good enough?" "How do I know?"



Atlas Camera Optimization Suite Optimize Camera Architectures to Improve Computer Vision



Atlas Automated Workflows

Sensor Module Qualification



Image Quality Optimization / Certification



Reduce lab setup and effort

Ensure system reqs are met

- Optimize camera IQ in days
- Establish IQ pass/fail "bar"

Computer Vision Optimization



 Optimize cameras to maximize computer vision accuracy



Atlas Optimizes Cameras for IQ and Computer Vision





Efficient

Get results in just days



Optimal

Maximize CV results



Scalable

Any CV task and camera



Objective

Results driven by clear metrics



9

Atlas Camera Optimization Suite Cloud-Enabled Workflow



Atlas Workflow for Image Quality and Computer Vision







11

Atlas Automates Manual Camera ISP Tuning







Atlas Scales to Your Needs





Atlas and User Components





Atlas Client Components: ISP, CV/IQ Processor, KPI





Use HTTP to call Component methods



[CASE STUDY] Automotive Tier 1 Front-facing Camera Optimized for Computer Vision



Front-Facing System: V3H ISP Atlas-Optimized for YOLOv4



- ISP optimization for YOLOv4 object detector
- 2500 images total, 90 used for the optimization set
 - \rightarrow Remaining images were used for validation
 - \rightarrow Selection balanced lighting, class and object size distribution
- Dataset built from 4 captures during:
 - 1. Midday: Bright daytime images
 - 2. Afternoon: Bright daytime to afternoon
 - 3. Dusk: Afternoon to dusk
 - 4. Night: Night low light





Computer Vision Optimization: YOLOv4

Optimization Loss Function

A single loss function was used to maximise Mean Average Precision of the object detections.

```
loss = 1 - mAP(loU>.5)
```





Image Quality Tracking

Charts and test patterns included in dataset for each trialed configuration to measure...

- Color Accuracy / Saturation
- Tonal Response
- SNR
- MTF
- Overshoot / Undershoot
- etc....

While ISP was optimized for CV accuracy...

IQ factors are also tracked through the optimization runs















Accuracy Results for YOLOv4 Detector vs. IQ Tuned Baseline

| mAP (IoU>.5) | Vendor Tuned ISP | Atlas Optimized ISP |
|-----------------|------------------|------------------------|
| Midday | 0.348 | 0.367 |
| Afternoon | 0.210 | 0.341 |
| Dusk | 0.168 | 0.393 |
| Night | 0.005 | 0.286 |

mAP (IoU >0.5)



Atlas Optimization Summary

- 2% 28% mAP Improvement vs. Baseline
- Final optimization: 1000 Trials in ~36hrs





















Immediately Improve Your Vision System







Questions? Thank You!

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