

The logo for the 2021 Embedded Vision Summit Virtual. It features the year '2021' in a light blue font at the top. Below it, the word 'embedded' is in a smaller, dark blue font. The word 'VISION' is in a large, bold, dark blue font, with the letter 'O' replaced by a colorful circular graphic composed of many small dots. Below 'VISION' is the word 'summit' in a dark blue font. At the bottom, the word 'VIRTUAL' is in a green font, followed by a vertical bar and the dates 'MAY 25-28' in a light blue font. The entire logo is set against a white background with a subtle grid pattern, which is itself centered within a larger graphic of overlapping green and yellow geometric shapes.

2021
embedded
VISION
summit®
VIRTUAL | MAY 25-28

Alternative Image Sensors for Intelligent In-cabin Monitoring, Home Security and Smart Devices

Dr. Petronel Bigioi
XPERI

The XPERI logo, featuring the word 'XPERI' in a bold, sans-serif font. The 'X' is pink, and the remaining letters 'PERI' are purple. A small yellow dot is positioned above the 'X'.

XPERI®

Portfolio of Trusted Brands



dts

Sound, Connected
Media, Imaging, and
Computer Vision
Solutions



HD Radio

Digital Broadcast
Radio and Connected
Car Services



IMAX
ENHANCED

Creation and Delivery of
Immersive Cinematic
Entertainment



invensas

Semiconductor and
Interconnect Packaging
Technology and
Solutions



TESSERA

Semiconductor
Intellectual Property
Licensing



TiVo

Entertainment Software,
Consumer Hardware,
Data and Advertising
Solutions

- Visible light constitutes a small portion of the electromagnetic spectrum, and image frames capture an instant in time rather than a continuous sequence.
- This motivates exploring beyond the visible and finding alternatives to the use of frame-based imaging.
- What important information do we miss with frame based visible imaging?

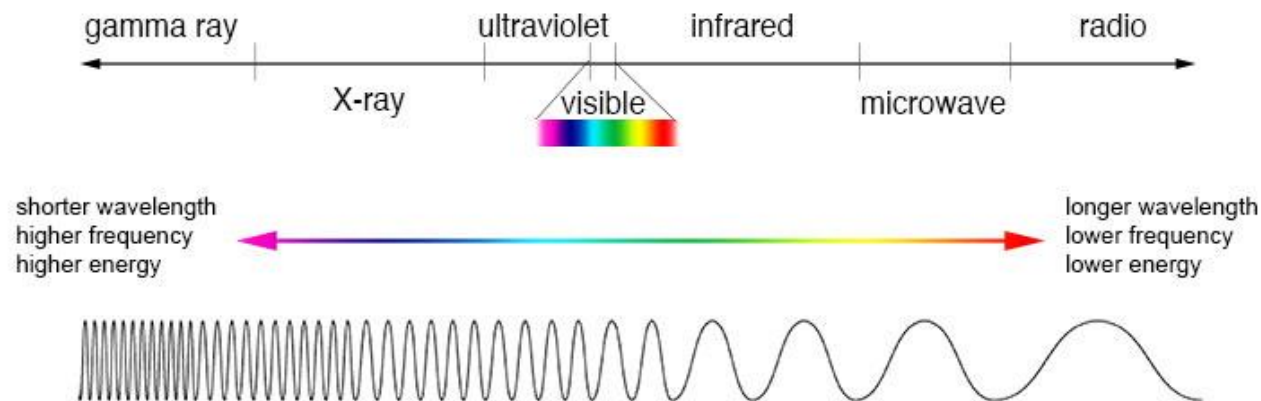
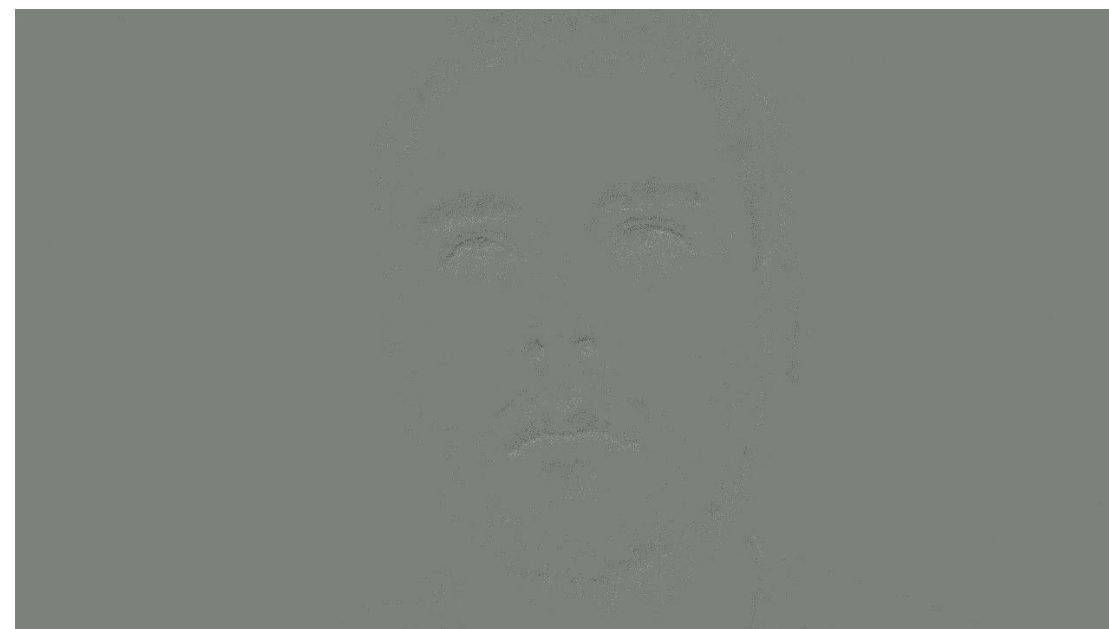


Image Credit NASA Explore

- Event cameras report light intensity changes
- Each pixel responds only to motion or changes in the scene
- Asynchronous “events” instead of frames

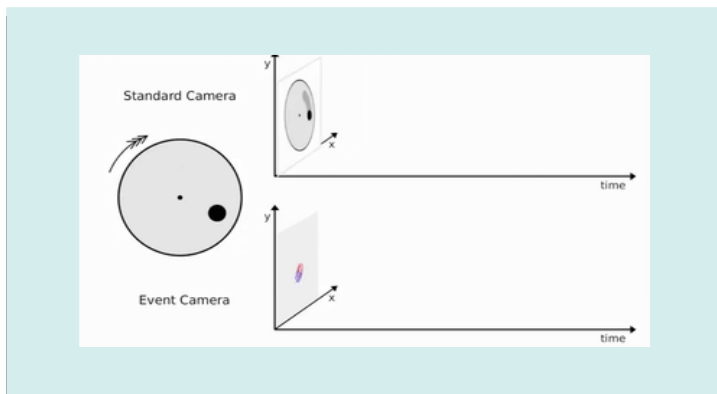
Event Stream

| time | x | y | polarity |
|------------------------|------------------------|------------------------|------------------------|
| 1.1177435000000000e+07 | 7.0600000000000000e+02 | 1.3600000000000000e+02 | 1.0000000000000000e+00 |
| 1.1177437000000000e+07 | 4.8500000000000000e+02 | 5.9100000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177446000000000e+07 | 7.6600000000000000e+02 | 3.0400000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177465000000000e+07 | 6.2900000000000000e+02 | 1.7900000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177485000000000e+07 | 8.6100000000000000e+02 | 1.8600000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177489000000000e+07 | 6.5100000000000000e+02 | 1.2200000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177489000000000e+07 | 7.0200000000000000e+02 | 4.8400000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177489000000000e+07 | 7.3000000000000000e+02 | 1.5900000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177494000000000e+07 | 7.6500000000000000e+02 | 4.9300000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177494000000000e+07 | 7.9800000000000000e+02 | 1.9900000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177495000000000e+07 | 6.9800000000000000e+02 | 3.9500000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177499000000000e+07 | 7.8800000000000000e+02 | 1.0800000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177509000000000e+07 | 6.5700000000000000e+02 | 1.1700000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177510000000000e+07 | 6.8400000000000000e+02 | 1.8700000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177525000000000e+07 | 6.9100000000000000e+02 | 3.8400000000000000e+02 | 1.0000000000000000e+00 |
| 1.1177550000000000e+07 | 6.9900000000000000e+02 | 1.4400000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177558000000000e+07 | 7.0000000000000000e+02 | 1.6900000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177559000000000e+07 | 8.3300000000000000e+02 | 9.5000000000000000e+01 | 0.0000000000000000e+00 |
| 1.1177562000000000e+07 | 6.7600000000000000e+02 | 2.7800000000000000e+02 | 0.0000000000000000e+00 |
| 1.1177569000000000e+07 | 6.7300000000000000e+02 | 3.9600000000000000e+02 | 0.0000000000000000e+00 |



Much higher temporal resolution (microseconds)

- ▶ Event cameras can operate at the equivalent of $> 10,000$ fps
- ▶ Can capture fast moving objects with no motion blur or loss of information
- ▶ Video shows a reconstruction from an event-based camera compared with one from an NIR camera. Note the motion blur in the visible.



Reconstructed Events



Frames from NIR camera



Higher dynamic range (> 120 dB)

- ▶ Event camera can operate in extreme lighting conditions
- ▶ Operation under low lighting conditions is crucial for in-cabin monitoring, home surveillance and smart cameras
- ▶ Closer to dynamic range of the eye



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Responds to motion (asynchronous pixels)

- ▶ Enable adaptive framerates i.e. data is processed only when a scene has changed
- ▶ Ignores “unwanted” information i.e. static, unchanging objects. This is often an advantage but is also a disadvantage when static information is required.
- ▶ Reduces computational costs and memory usage
- ▶ We are normally only interested in changes in the state of the driver (driver monitoring) or changes in the scene (surveillance)



Dataset re-use – Training machine learning models

- ▶ Traditional frame-based images can be used to create synthetic event data for DNN training
- ▶ Both real and synthetic datasets can be used for neural network training
- ▶ Synthetic data simulators are more effective in comparison to frame-based cameras methods
- ▶ Event can be simulated using visible (RGB), near-infrared and even thermal images

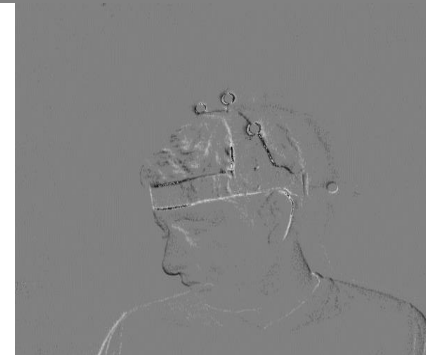
Synthetic Data



Camera Frames



Teza: "KOŚCIÓŁ KATOLICKI HAMUJE ROZWÓJ NOWOCZESNEJ POLSKI".

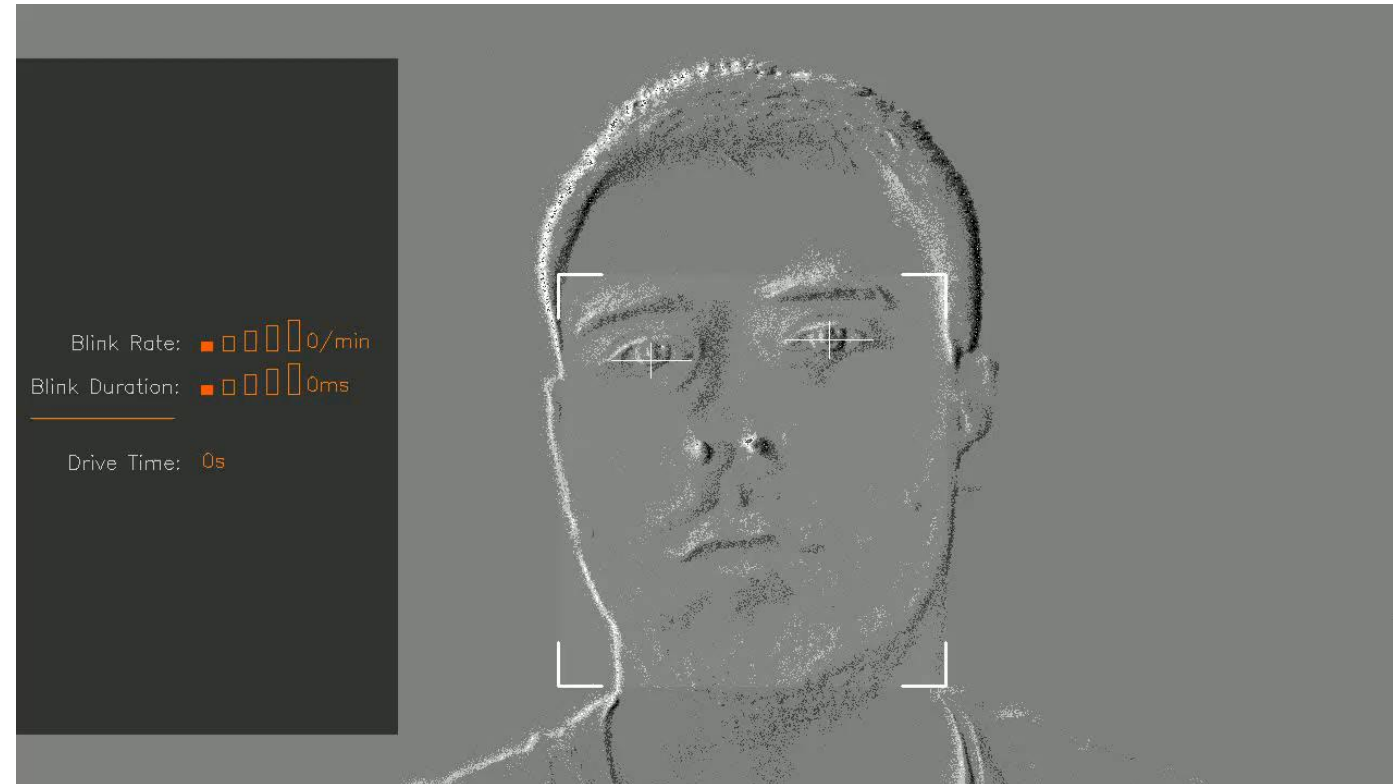


- ▶ Driver facial analytics
- ▶ Adaptive framerate based driver motion (video slowing effect with faster motion)

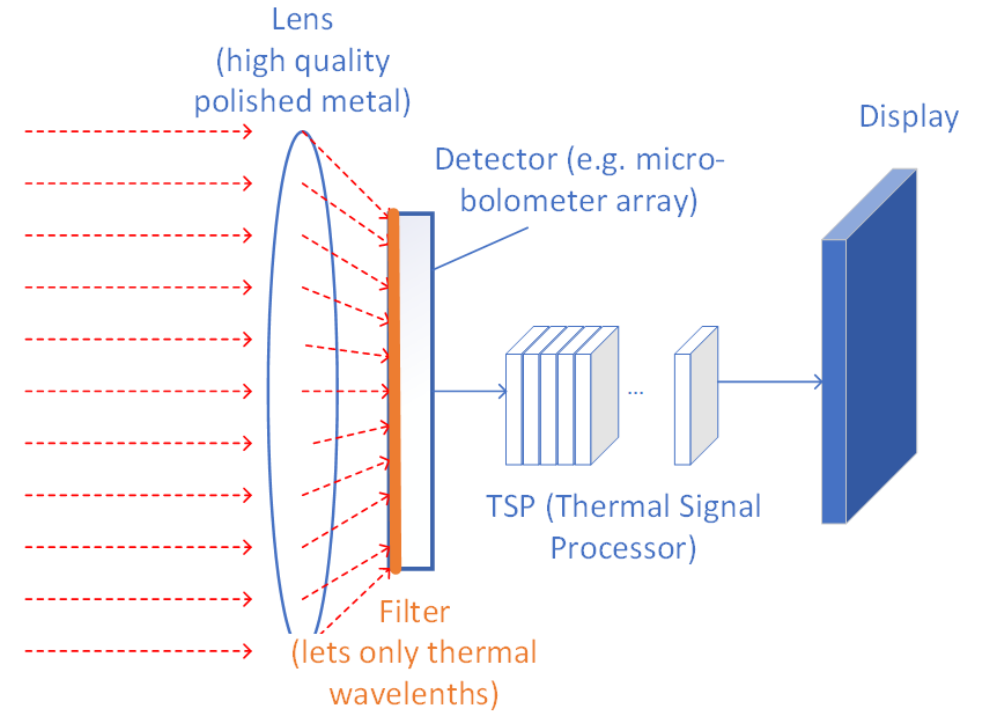
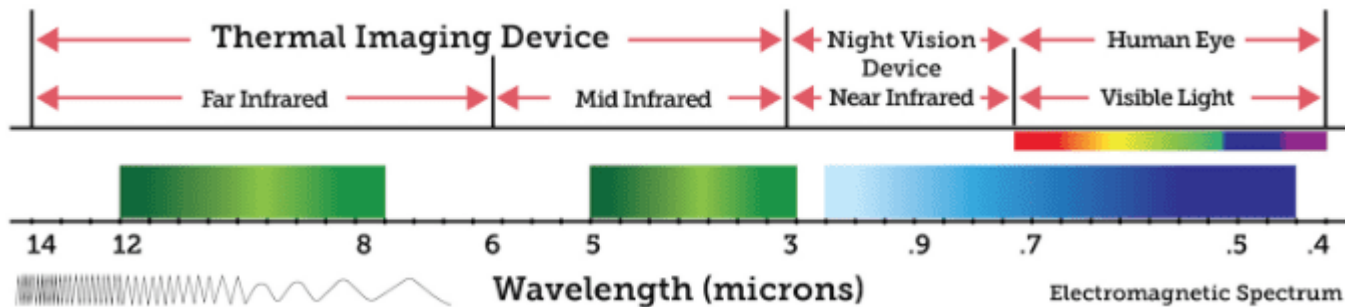


- ▶ Face/Eye detection
- ▶ Head pose estimation
- ▶ Eye gaze estimation
- ▶ Occlusion detection

- ▶ Eye blinking patterns can be analysed at a desired rate
- ▶ Possible features include blink frequency, duration, speed, downward/upward duration and speed, time closed etc.



- Thermal cameras detect far infrared energy i.e. heat
- They typically capture wavelengths between 8-14 μm
- Microbolometer array sensors are used and respond to heat changes
- Thermal reflections can be a problem and different materials have different emissivity.



- ▶ Provide information beyond the visible and near-infrared light spectrums
- ▶ They can operate under any lighting conditions
- ▶ Disadvantages include low resolution, increased cost, and the difficulty of determining certain ocular parameters such as eye gaze.

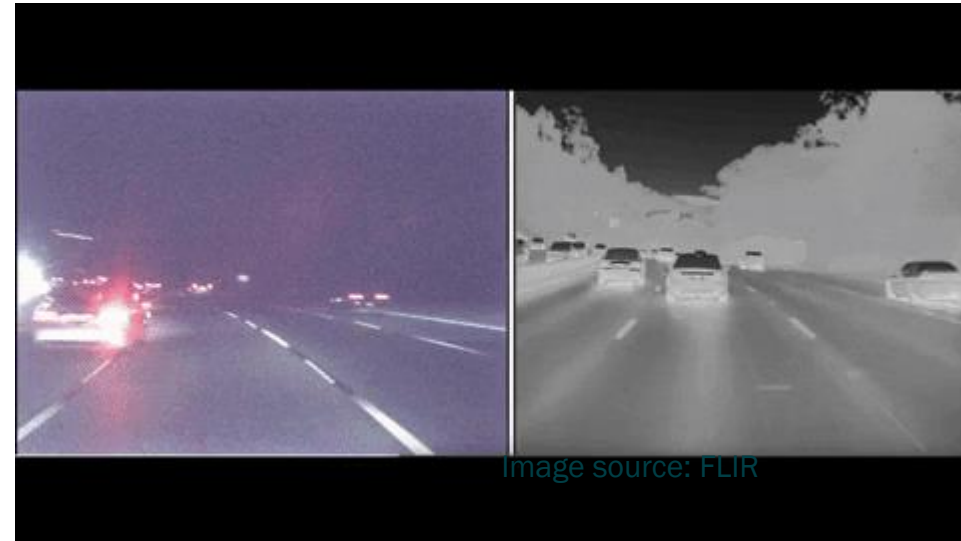
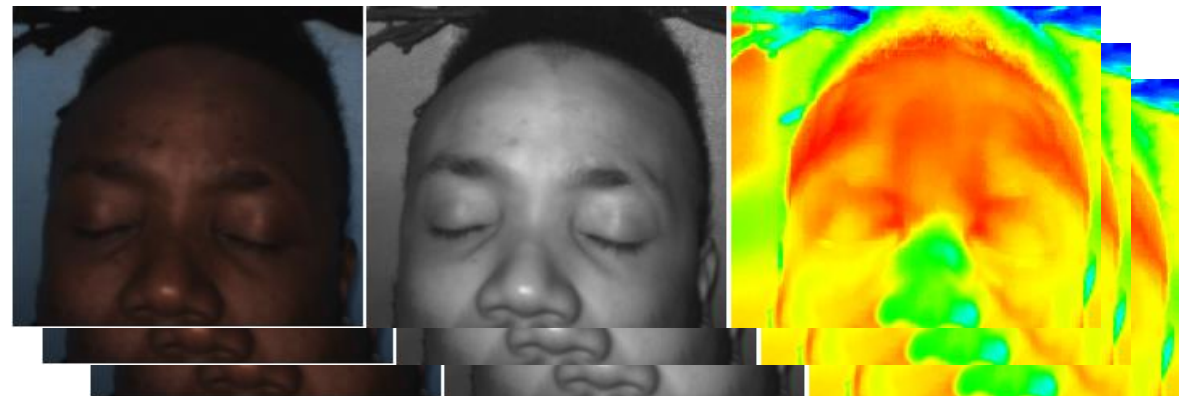


Image source: FLIR

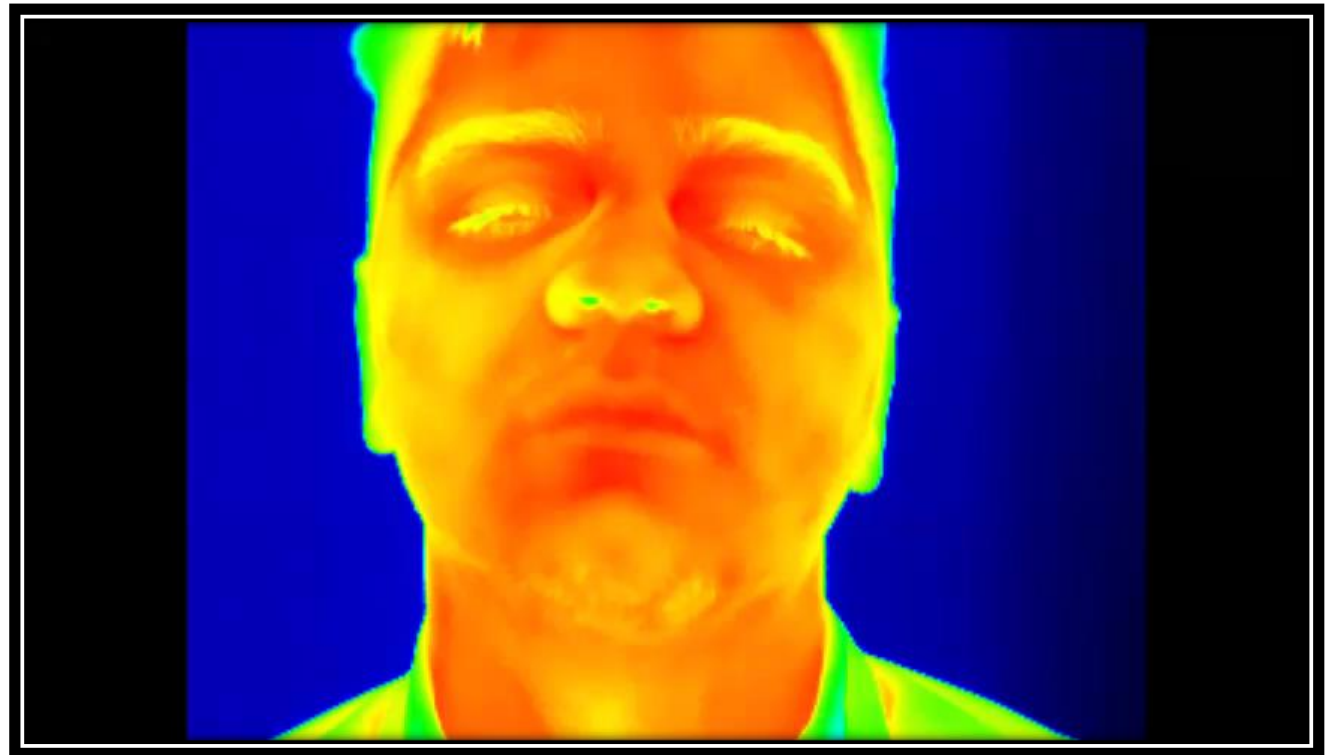
Visible domain
-color-

NIR domain
-structure-

FIR domain
-activity-



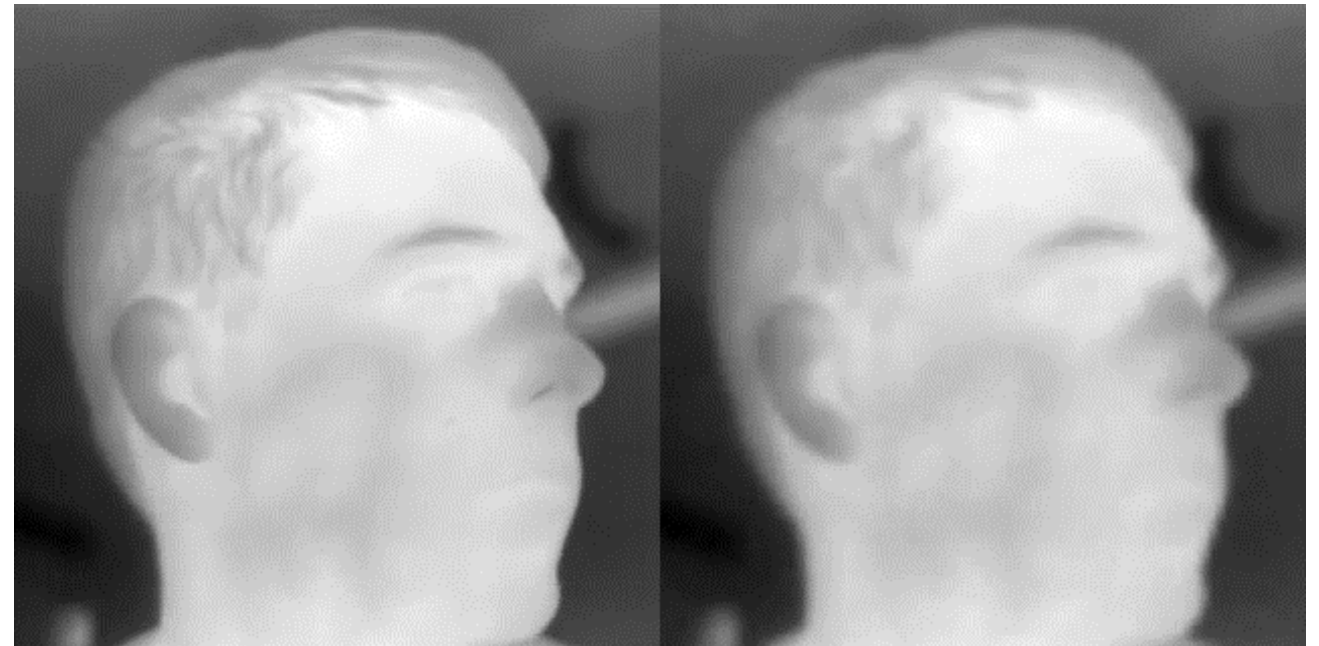
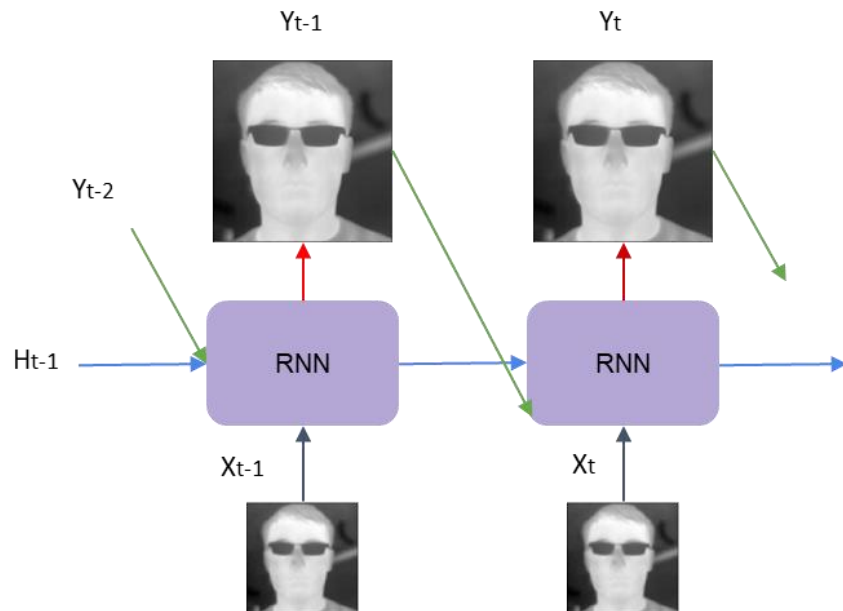
- ▶ Thermal cameras enable us to capture physiological features beyond the capabilities of visible or NIR cameras
- ▶ Advanced vital sign monitoring:
 - ▶ Breathing rate
 - ▶ Heart rate
 - ▶ Temperature
 - ▶ Enhanced Drowsiness or attentiveness
 - ▶ Skin health



Thermal Cameras

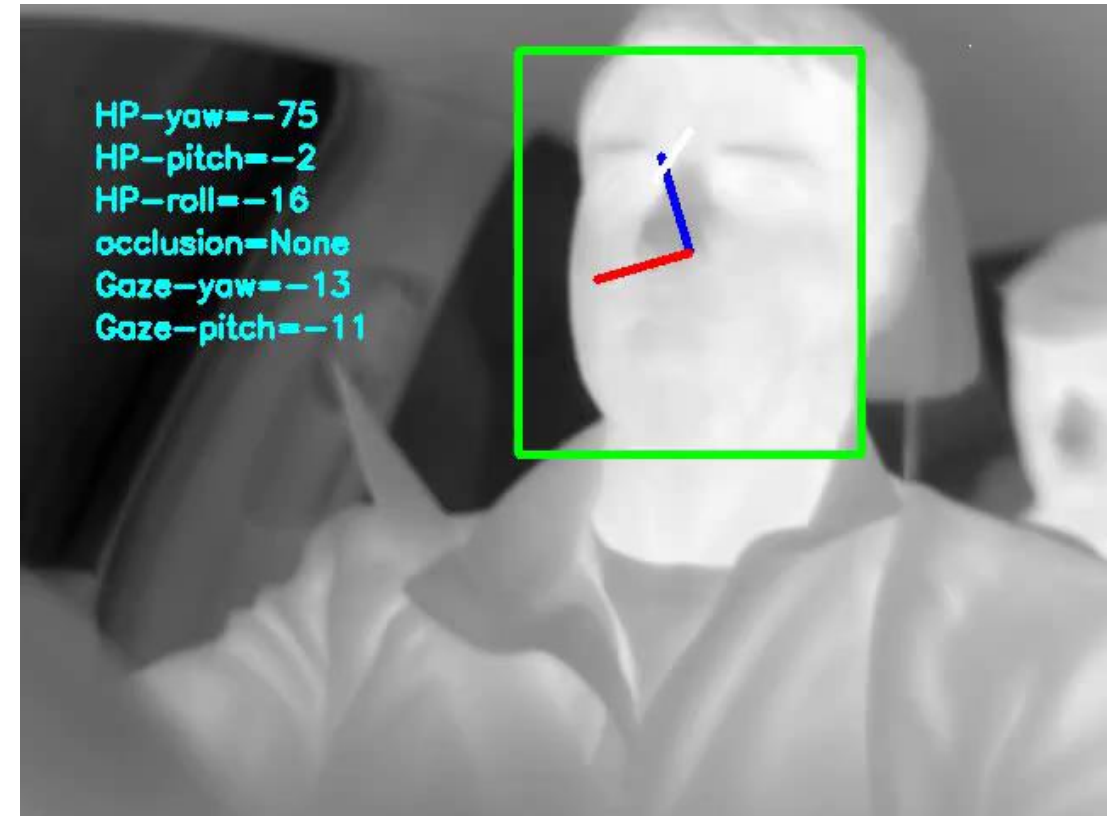
Thermal Super-Resolution

- Recovering high-resolution images from single or multiple low-resolution images
- Super-Resolution includes de-noising, de-blurring and up-sampling
- Supports the use of cheaper, lower-resolution thermal cameras
- Convolutional Neural Networks provide state-of-the-art and real-time performance

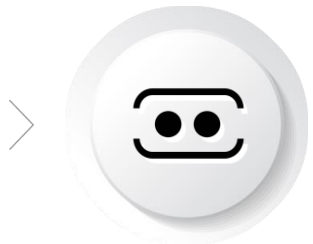


Early driver monitoring system prototype from Xperi built with a thermal camera supporting features such as:

- Head Pose estimation
 - Yaw, pitch and roll angles
- Occlusion detection
 - glasses, masks, phones etc.
 - Some objects are easier to detect in thermal compared to visible or near-infrared
- Liveness detection
 - Anti-spoofing

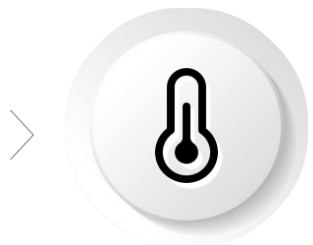


ALTERNATIVE SENSING



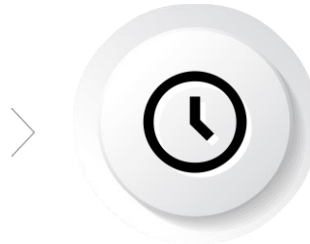
DUAL SYSTEM CAMERA

- narrow + wide configuration
- Face recognition + IRIS (Bank and payment grade biometrics)



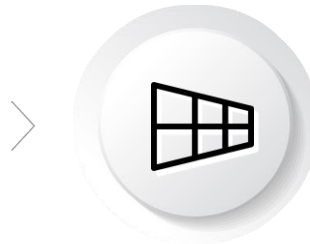
THERMAL SENSING

- vital sign monitoring
- driver comfort monitoring



TIME EVENT CAMERA

- precise eye analytics
- NIR camera substitute for DMS



DEPTH SENSING

- airbag deployment + body estimation
- 3D Facial Recognition, payment-grade + anti-spoofing



MMW RADAR

- reliable presence sensing

- <https://www.prophesee.ai/>
- <https://www.prophesee.ai/category/dataset/>
- <https://www.helias.eu/>
- <https://doi.org/10.1016/j.neunet.2021.03.019>
- <https://doi.org/10.1109/QoMEX48832.2020.9123135>
- https://github.com/uzh-rpg/rpg_e2vid
- https://github.com/uzh-rpg/rpg_vid2e
- <https://www.flir.eu/oem/adas/adas-dataset-form/>
- <https://dts.com/autosense/>

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Thank You!

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XPERI

XPERI Market Presence

DTS® and HD Radio™ audio and broadcast data technologies



Over 2.65 billion devices and vehicles

TiVo® and DTS® enabling premium entertainment



Over 5 billion hours of video consumed

DTS® imaging hardware and software



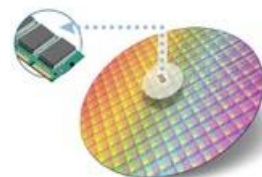
Over 3.65 billion devices and vehicles

Invensas ZiBond® and DBI® interconnect technologies



Over 1 billion smartphones

Tessera packaging/
interconnect IP



Over 100 billion chips