



Build Smarter, Safer and Efficient Autonomous Robots and Mobile Machines

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Agenda



- Introduction
- Key challenges
- Key care-about
 - Sensing
 - System design and performance
 - Functional safety
- Development

Introduction | Smarter, more efficient, safer



Autonomous mobile robots

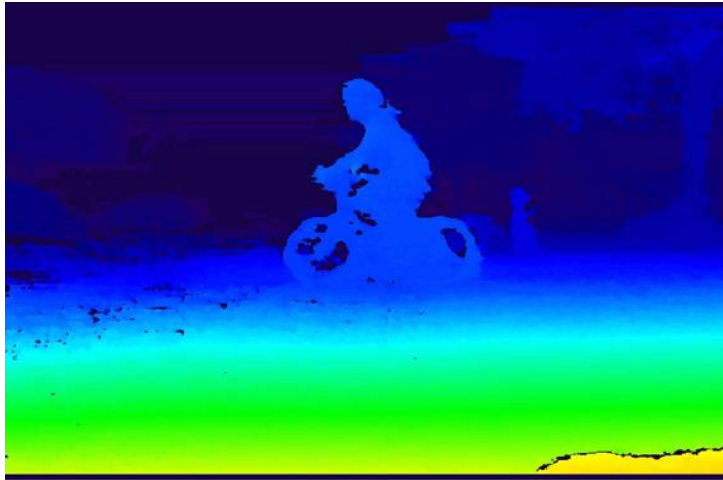


Autonomous delivery robots



Construction, excavation, agriculture

Introduction | Technology enablers



3D perception



Artificial intelligence



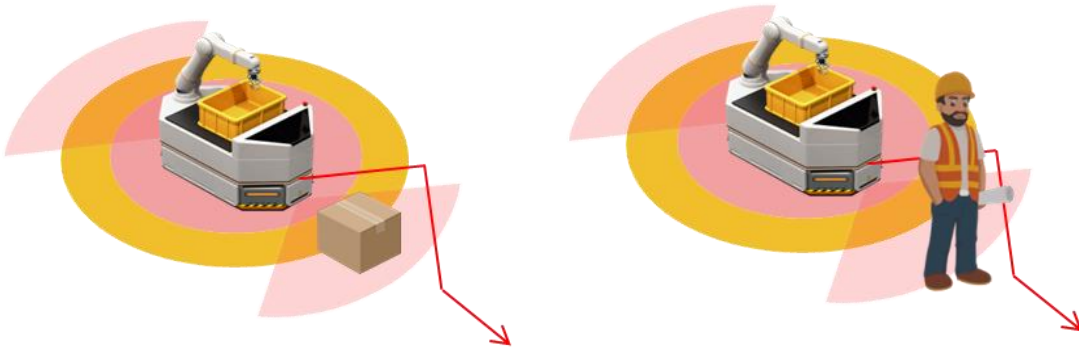
Functional safety

Key Challenges

Key challenges | Safe operation

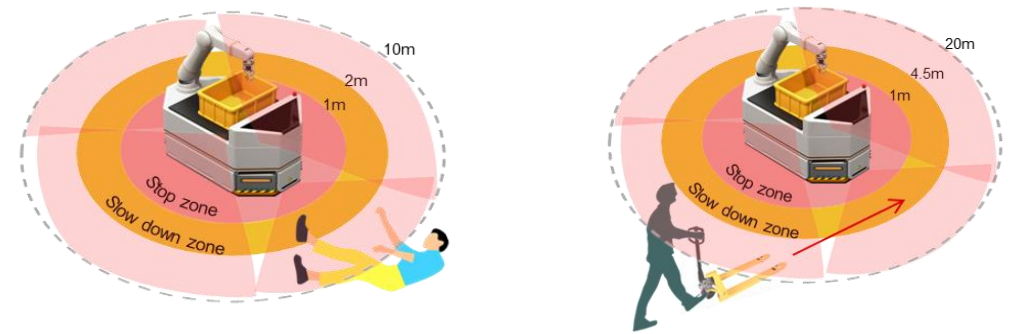


Collision Avoidance



- Detect humans and obstacles
- Navigate around them

Human Presence Detection



- Stop when people are in the safety bubble
- Resume when people are out of the safety bubble

Key challenges | Accurate & affordable sensing



Radar



Pros:

- Cheaper
- Works in all weather

Cons:

- Poor angular resolution

Lidar



Pros:

- Better precision and accuracy

Cons:

- Costly, consumes more power
- Poor results in bad weather
- 2D Lidar has poor resolution

Vision



Pros:

- Cheapest and best resolution
- Classify objects & scenes well

Cons:

- Computationally intensive
- Requires good light sources

Key challenges | System design and complexity



System challenges

- High-performance / low-latency processing at low-power
- Small form-factor, ruggedized design
- Cost-optimized design

Application challenges

- Programming of hardware accelerators
- AI development
- Functional safety software

Key care abouts

Key care-about | Sensing with mmWave radar



TI mmWave	Robotics Benefits
3D presence detection	<ul style="list-style-type: none">• True 3D information (range, velocity and angle) of objects vs. LIDAR/ToF used mainly for distance measurement• Quickly detect and prevent possible collisions minimizing machine downtimes
<u>Up to IEC 61508 SIL-2 compliant</u>	<ul style="list-style-type: none">• Helps enable human presence detection that has traditionally been solved by expensive safety certified LiDAR sensors
Accurate glass detection	<ul style="list-style-type: none">• Improve reliable detection of glass walls/doors over existing sensors that "see" through them
Wide azimuth area coverage	<ul style="list-style-type: none">• Create 360-degree detection zones around the robot to prevent collisions with humans to minimize injury and reduce machine downtimes
Robust in challenging environments	<ul style="list-style-type: none">• Increase reliability over existing vision/LiDAR based sensors in conditions such as rain, dust, smoke, complete darkness or in the glare of sunlight

Complement or displace established sensor solutions with up to SIL-2 certified TI mmWave sensors

Key care-about | System design with TDA4x



Enhanced Safety

- Hardware and software solutions enabling up to SIL-3 and ASIL-D designs

Energy efficient AI & sensor fusion

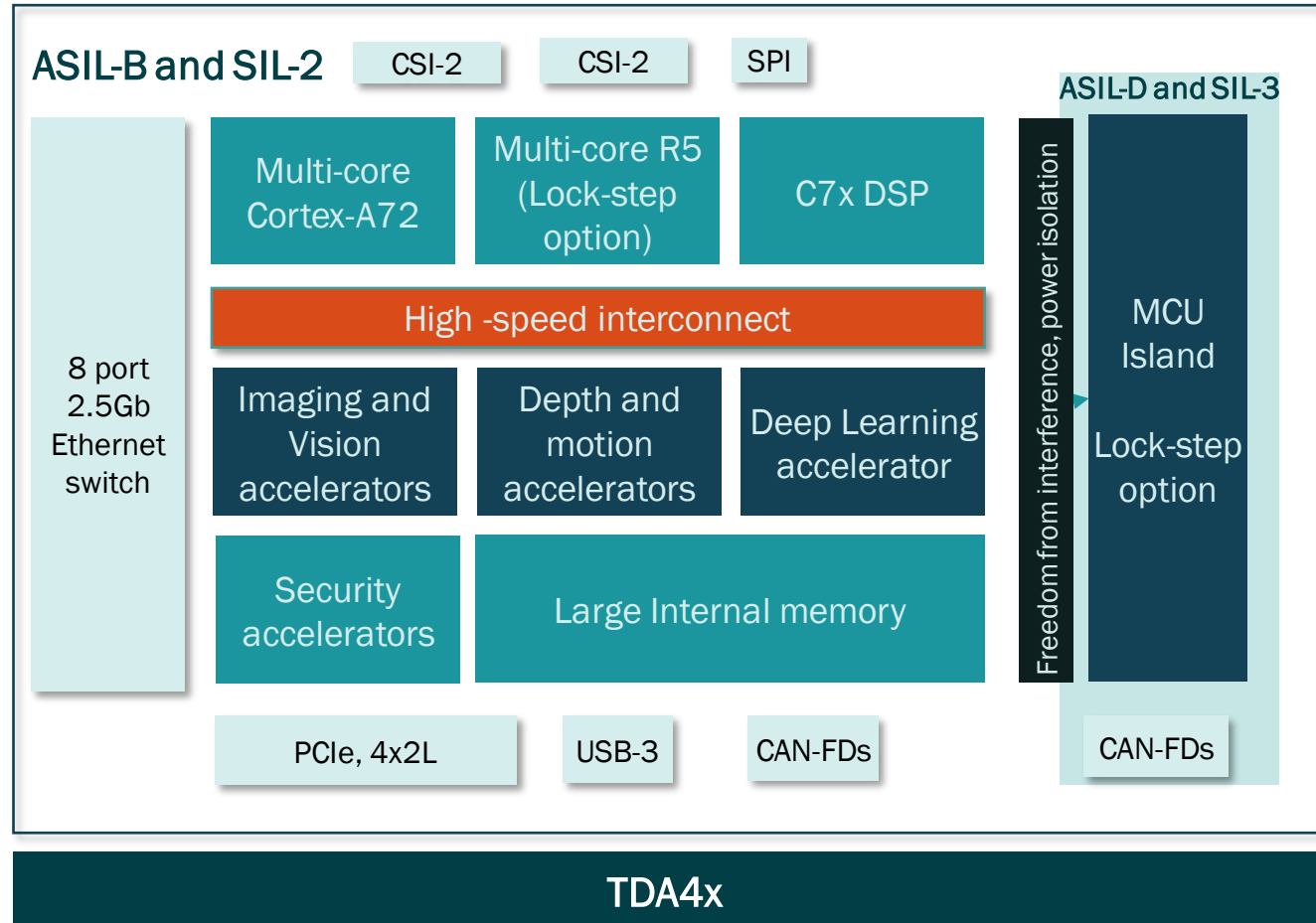
- Computer vision, deep learning accelerators & DSP cores delivering industry-leading performance at low power

Affordable design

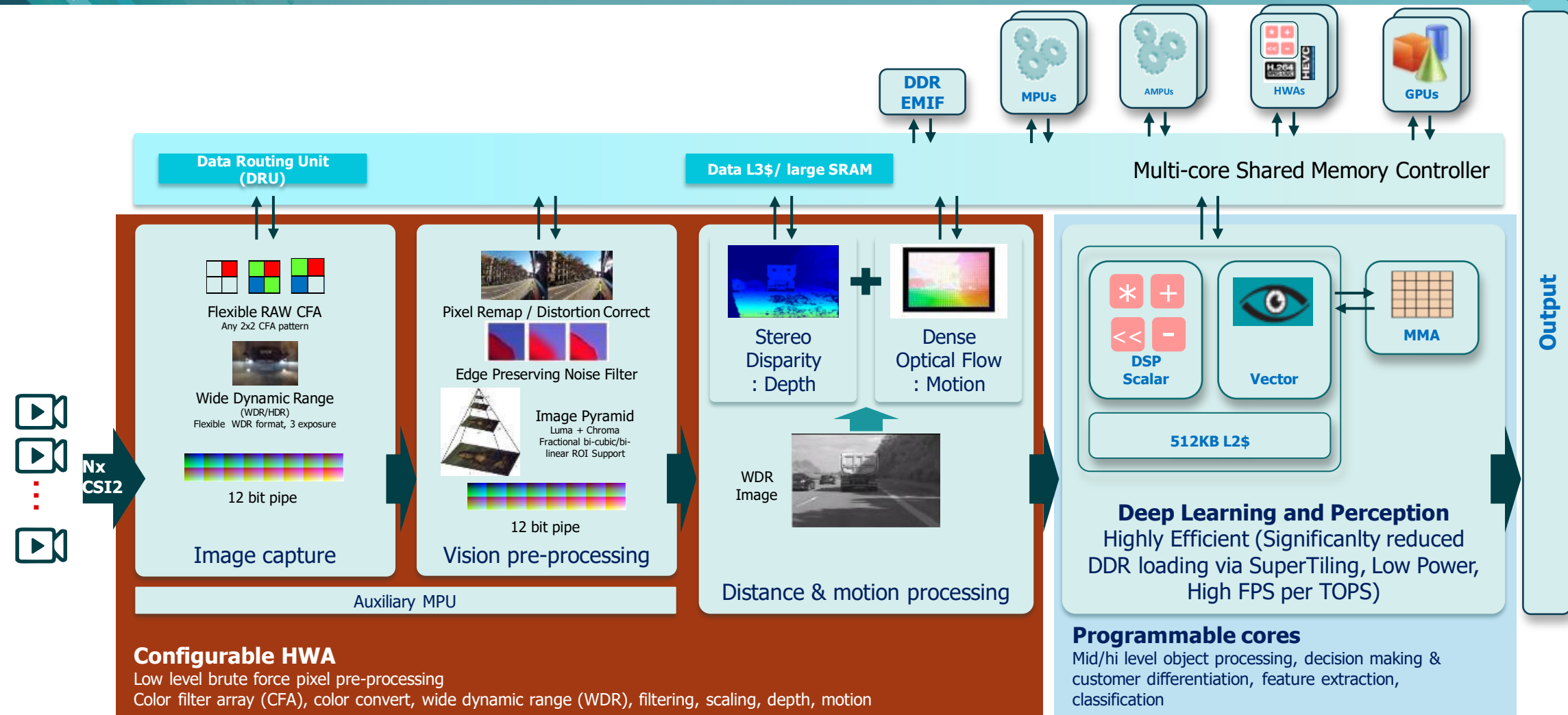
- High levels of integration in a single chip reduces system complexity and cost.

Faster development

- Open-source software, tools, SOM and eco-system enable faster-time-to-market



Key care-abouts | System performance with TDA4x



Key care-about | Functional safety with TDA4x



Architecture

- Independently certified safety development process for ISO26262 and IEC 61508
 - ASIL-D/SIL-3 systematic capability
- Built-in hardware diagnostics
- Peripherals and architectures designed for end system safety capabilities

Software

- Scalable across products
- TUV certified safety software process
- Safety diagnostic library
- Safety diagnostics reference and examples
- Self test libraries
- SW FMEDAs, code coverage, traceability reports
- Compliance support packages
- Compiler qualification kit
- FreeRTOS to SafeRTOS
- AutoSar and MCAL support

Collateral

- Device safety manual
- Configurable FMEDA
- Safety analysis report
- Safety assessment certificate
- Trainings
- White papers and application notes
- Safety-enabled demos

Development

Easy development with industry standard frameworks



Application layer

3D perception

Localization

Obstacle detection

Object tracking

Navigation

Python and C++ programming

Industry standard APIs and frameworks



TI tools and middleware for hardware acceleration

TI Edge AI processor

Arm® Cortex®-A

DSP

Deep learning

Imaging

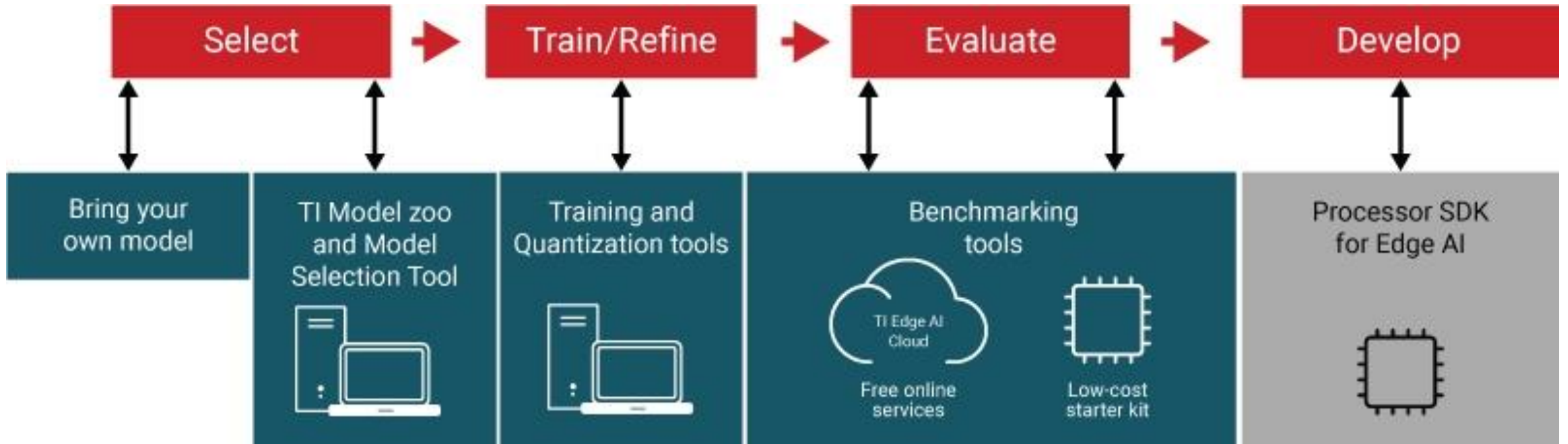
Vision

Multimedia

hardware accelerators

Full software from TI makes applications development much easier!

TI Edge AI | Extensive tools from TI for faster DL model development and deployment



Free end-to-end TI proprietary tools for faster AI model development and deployment

TI Edge-AI cloud | Free on-line service for deep-learning model selection, deployment and benchmarking



Welcome to TI Edge AI Cloud

You are now connected to a **Jacinto™ TDA4VM processor** evaluation module.

Find your model

Learn performance statistics

Compare model performance

Find the model that best meet your performance and accuracy goals on TI Processor from TI Model Zoo. Learn current performance statistics of models such as FPS, Latency, Accuracy & DDR bandwidth.



[Model selection tool](#)

Get model benchmarks

The following Notebooks let you access benchmarks for pre-compiled and custom models

Model performance

Using a pre-compiled model from TI Model Zoo, this example notebook lets you run inference on a TI Edge AI processor to get **latency, FPS, DDR bandwidth and power benchmarks**

Select task:

- ☒ Classification
- ☐ Detection
- ☐ Segmentation

Select runtime engine:

- ☒ TensorFlow lite
- ☐ ONNX runtime
- ☐ TVM

[Open notebook](#)

Model accuracy

Using a pre-compiled model from TI Model Zoo, this example notebook lets you run inference on a TI Edge AI processor to get **accuracy benchmarks**.

[Open notebook](#)

Custom models

This notebook lets you compile your own model and run inference on a TI Edge AI processor to get **latency, FPS, DDR bandwidth, power and accuracy benchmarks**.

Select runtime engine:

- ☒ TensorFlow lite
- ☐ ONNX runtime
- ☐ TVM

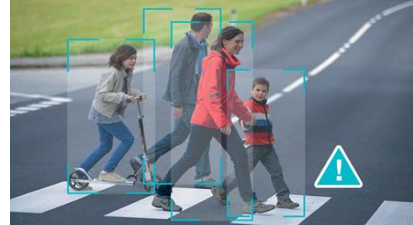
[Open notebook](#)

Faster deployment with out-of-box demos and production ready components



3D perception and navigation

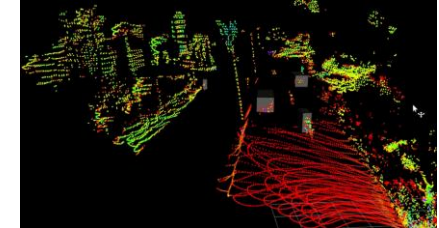
- ROS, ROS2 based, hardware and DSP accelerated demos
- Production ready GStreamer plugins, OpenVX and ROS nodes for offloading to hardware
- Functional safety complaint low-level drivers
- Community eco-system



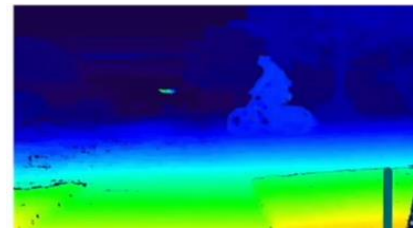
2D Object detection



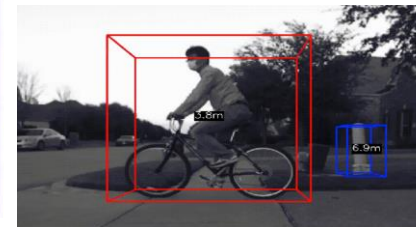
Semantic segmentation



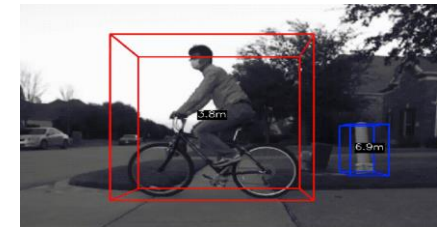
3D Point Cloud



Stereo depth estimation



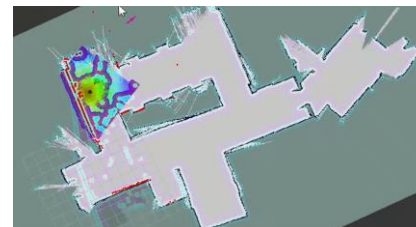
3D obstacle detection



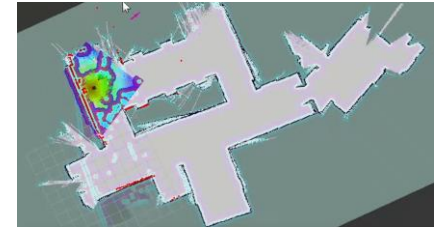
Pose estimation



AI-based localization

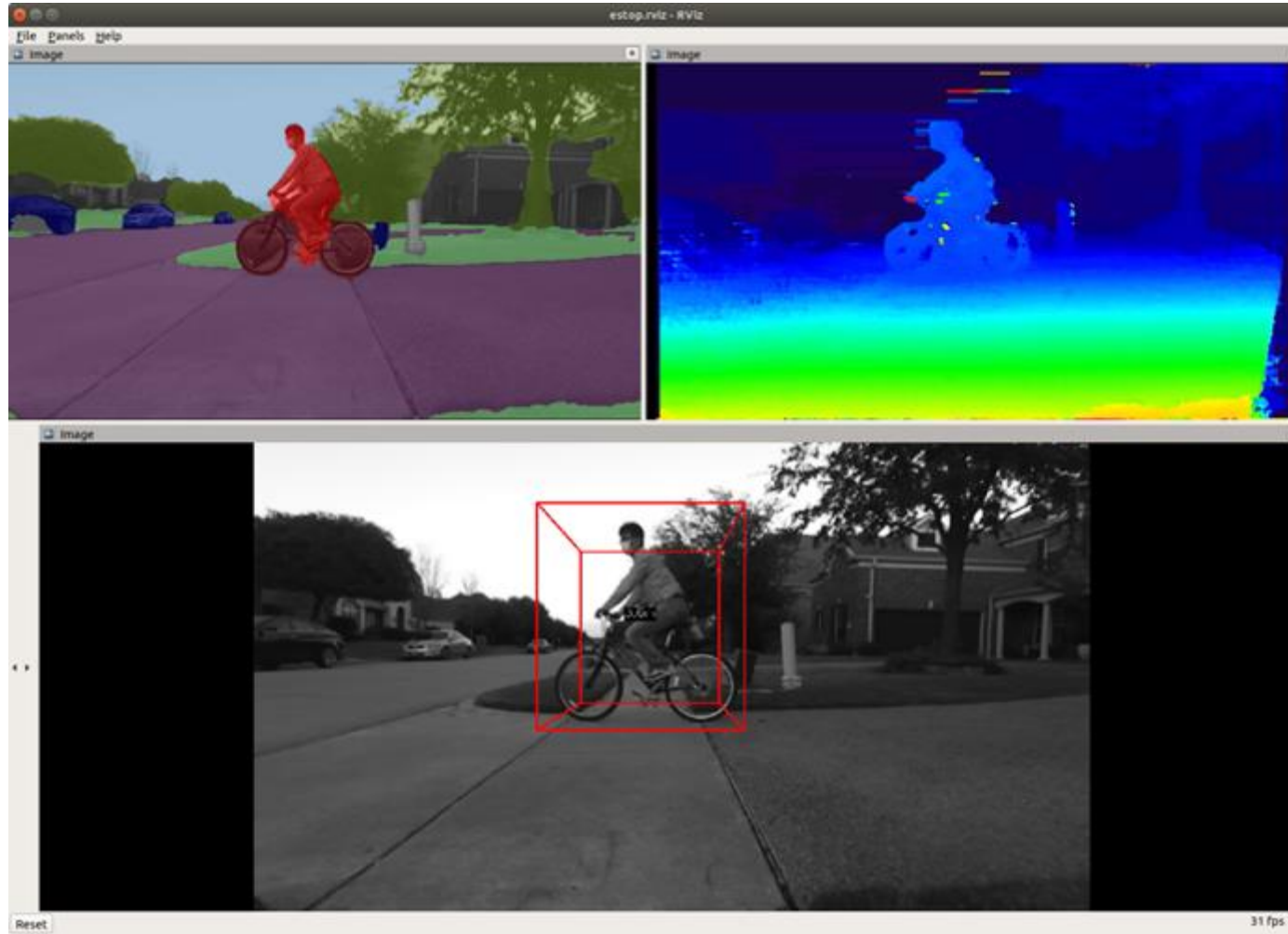


ORB SLAM



Autonomous navigation

Autonomous navigation and collision avoidance video



<https://training.ti.com/functionally-safe-autonomous-navigation-and-collision-avoidance-demo-using-tda4x-processors>

Conclusion



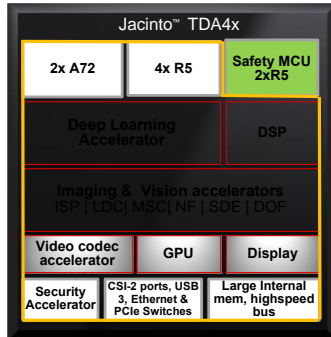
- Autonomous machine co-existing with humans are increasing productivity in all spheres of life
- Key technology enablers are 3D perception, AI and functional safety
- TI's functional safety compliant mmWave radar sensor increases reliability in seeing the obstacle where other sensors fails
- TI's TDA4x processor enable energy-efficient, functionally safe compliant sensor-fusion and AI powered autonomous mobile machines and robots.

Getting Started Resources

Development | Open-source software & tools



Processor for practical edge AI



ti.com/edgeai

Learn with free cloud tool



ti.com/edgeaicloud

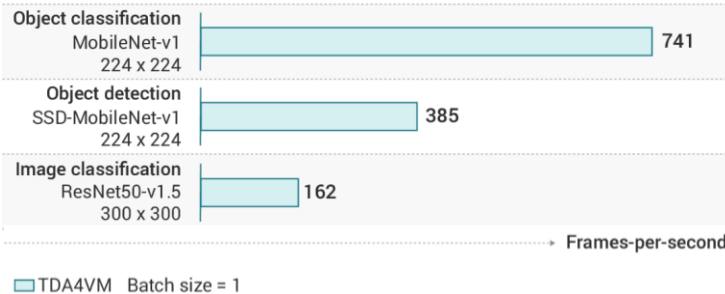
Build with 8 TOPS starter kit



P/N: SK-TDA4VM: \$249

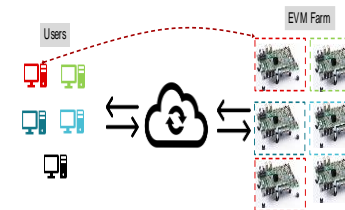
Energy efficient AI architecture

MLPerf inference benchmarks



Get started for free

- Example scripts
- TI Model Zoo
- Training videos

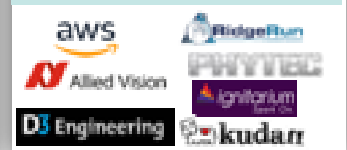


Fast Development Cycle

Industry standard APIs



3P Eco-system



Development | TDA4x processors



Edge AI evaluation

<https://dev.ti.com/edgeai>

<https://dev.ti.com/edgeaicloud>

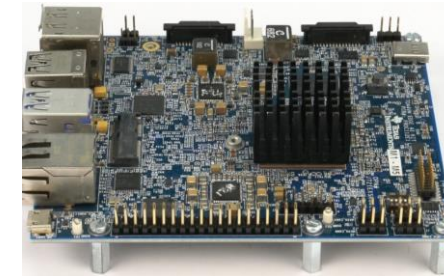
<https://dev.ti.com/edgeaiprojects>

Full development

Product Folder: <https://www.ti.com/product/TDA4VM>

Starter Kit : <https://www.ti.com/tool/SK-TDA4VM>

TDA4 EVM: <http://www.ti.com/tool/TDA4VMXEVM>



Software development kits

TI Processor SDK for edge AI – Seamlessly reuse and migrate Linux,
<https://www.ti.com/tool/download/PROCESSOR-SDK-LINUX-SK-TDA4VM#downloads>

<http://www.ti.com/tool/PROCESSOR-SDK-DRA8X-TDA4X>

Support

<https://e2e.ti.com>

Learn on <https://training.ti.com/process-monthly-webinar-series>



Evaluation modules

IWR6843 ISK (60 GHz)
IWR6843 AOP (60 GHz Antenna on package)
IWR1843 BOOST (77 GHz)

Reference examples/labs

Sense and avoid lab for collision avoidance
360° safety bubble with ROS lab for safe human presence detection

Accelerate path to production with 3P network

Designing TI mmWave made easier using 3rd party ecosystem
Industrial mmWave third-party search tool