



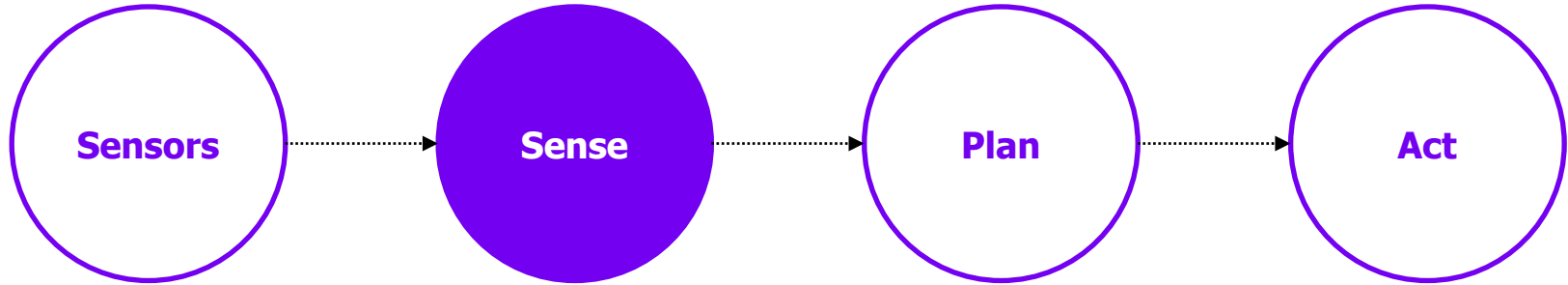
Developing an Efficient Automotive Augmented Reality Solution Using Teacher-Student Learning and Sprints

Jack Sim

CTO

STRADVISION

Vision perception for active safety driving features



SVNet is part of the perception stack in ADAS, which provides key information for next stages such as planning and control

SVNet, Cutting Edge AI Technology

Deep learning-based vision perception algorithm + own know-how in automotive applications



Strong Performance

Expand and refine target algorithm through the state-of-the-art learning techniques



High Efficiency

Light weight and compact DNN¹⁾
Algo Less computing resource required



Maturity

Multiple commercial projects with automotive OEMs for mass-production of vehicle models



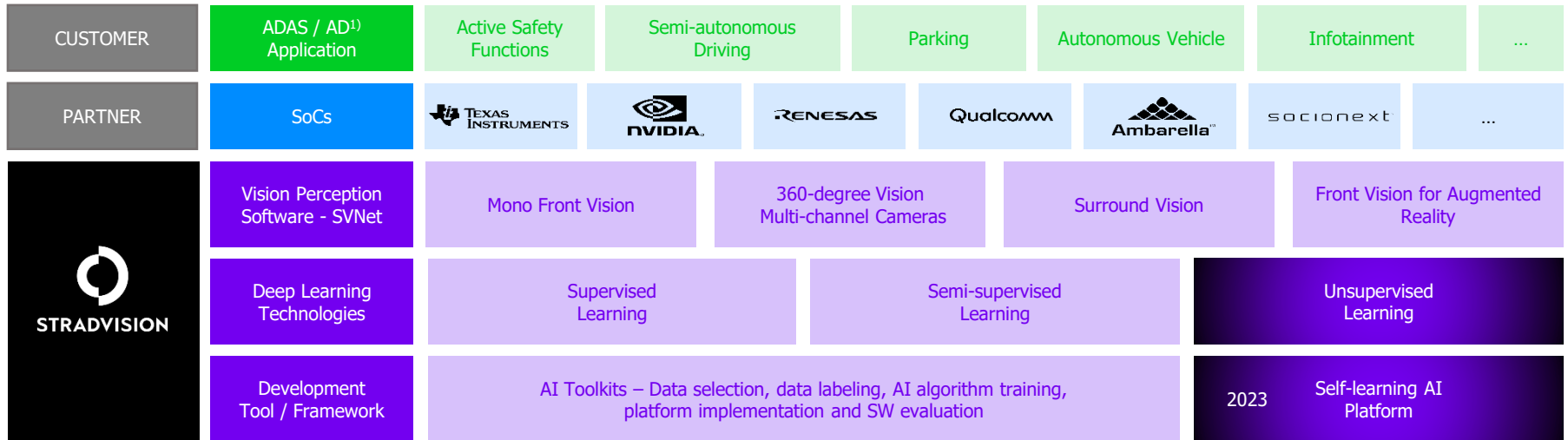
Industry Recognized Network

470+ patents with deep neural network
ASPICE²⁾ certification

DNN¹⁾ Deep Neural Network

ASPICE²⁾ Automotive Software Process Improvement and Capability dEtermination

Versatile software for flexible and customized applications in the automotive industry



1) ADAS: Advanced Driver Assistance Systems / AD: Autonomous Driving

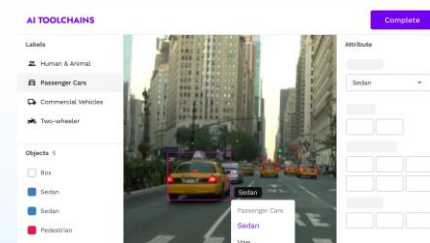
SVNet Product Lineup

1.ProDriver

2.ParkAgent

3.ImmersiView

4.CompliKit



EntryVision

BasicVision

CoreVision

UltraVision

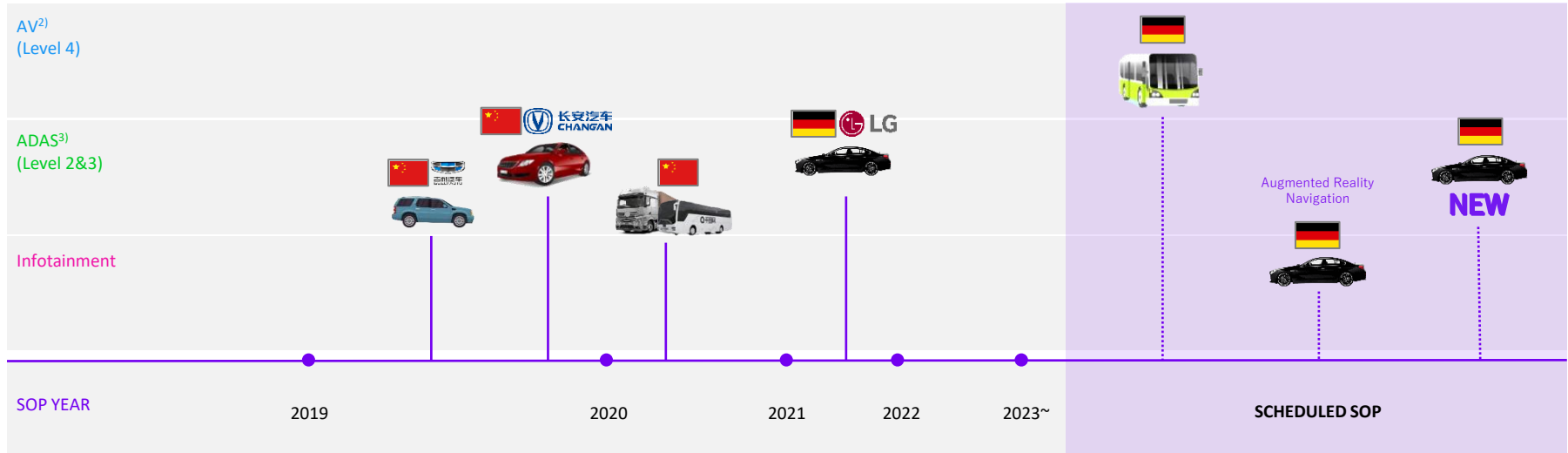
BasicAgent

AdvancedAgent

ValetAgent

Product Maturity – Design Wins with 13 OEMs

13 million vehicles in 50+ models on their way to the road with SVNet¹⁾ software embedded



SVNet¹⁾: STRADVISION Deep Learning Network AV²⁾: Autonomous vehicles ADAS³⁾: Advanced Drivers' Assistance Systems

Key Techniques of SVNet

SV SPRINT MODEL

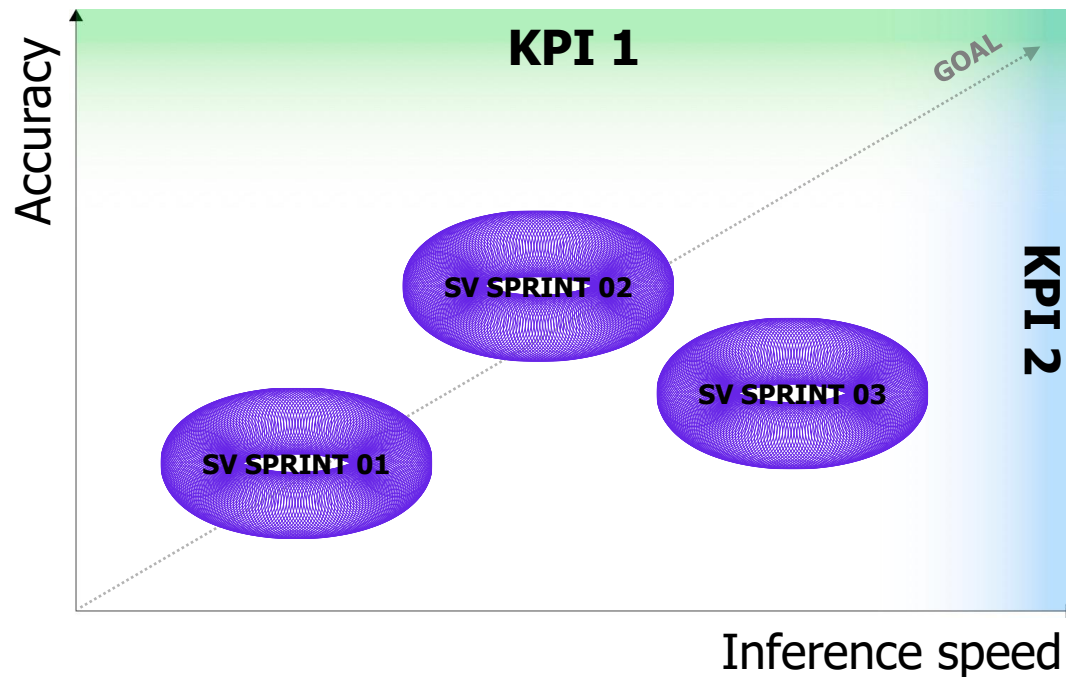
Prep Data

Prep Data



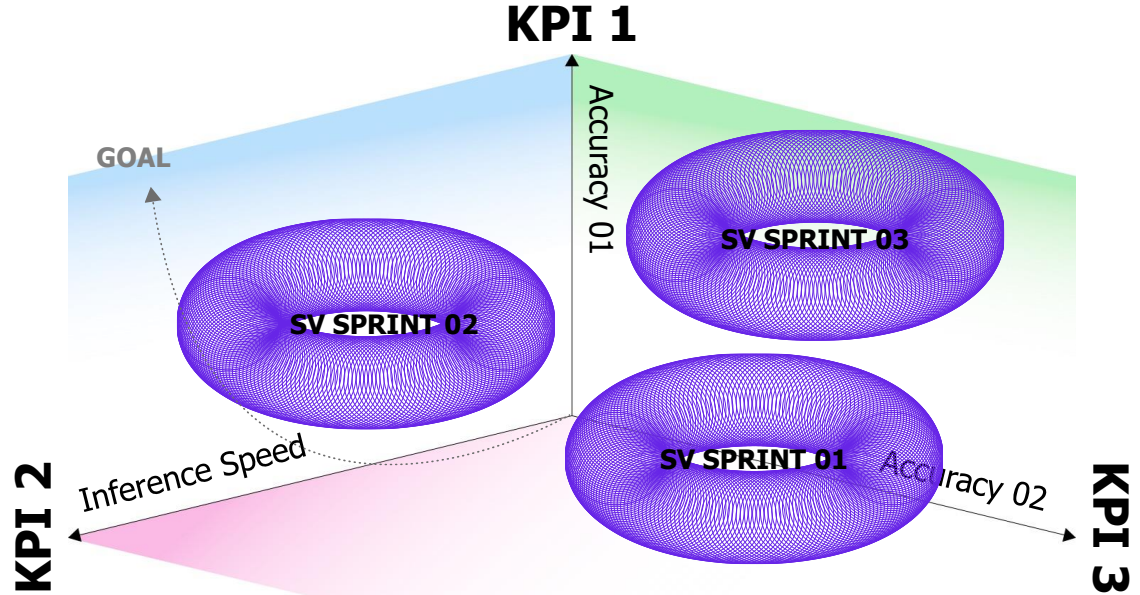
Challenges in Deep Learning Projects

- *Long* development cycles
- *Unpredictable* outcomes in each cycle (e.g., accuracy and speed)



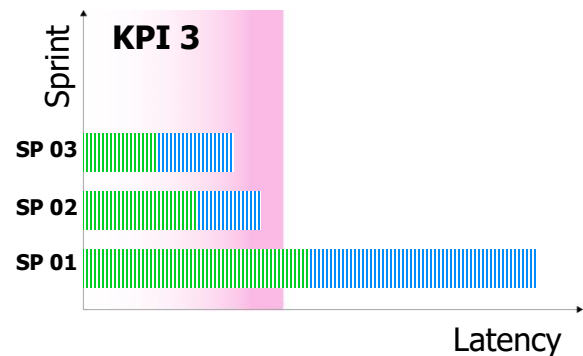
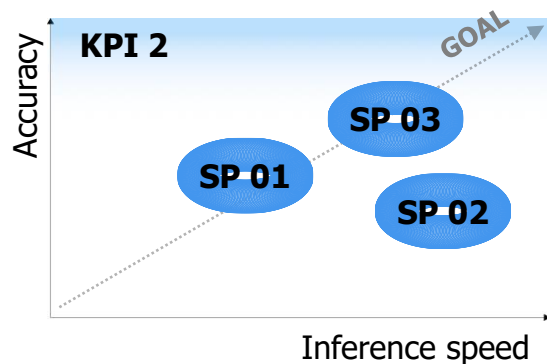
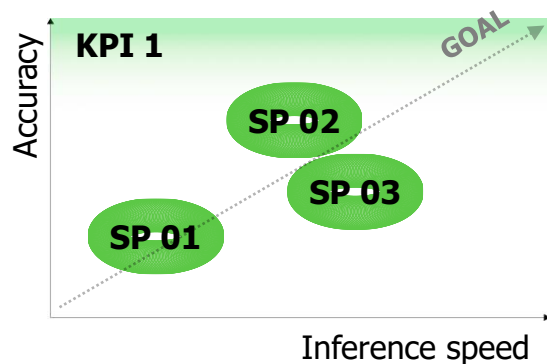
Even More Challenges: Multi-Task DL Projects

- *Looooonger* development cycles
- *Harder* to meet KPIs in *limited* time



Naïve Approach to the Multi-Task DL Projects

- Train individual networks on *separate datasets*
- *Shorten* development cycles
- Causing resource *allocation* issues
- Inference speed in Task 1 vs. Task 2

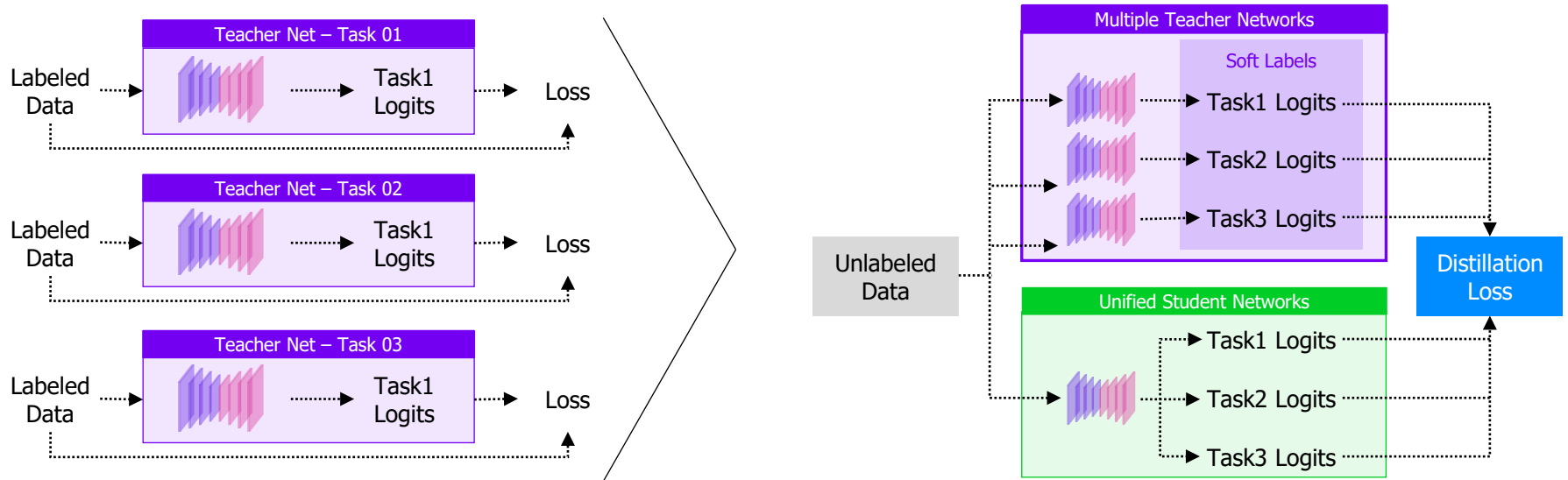


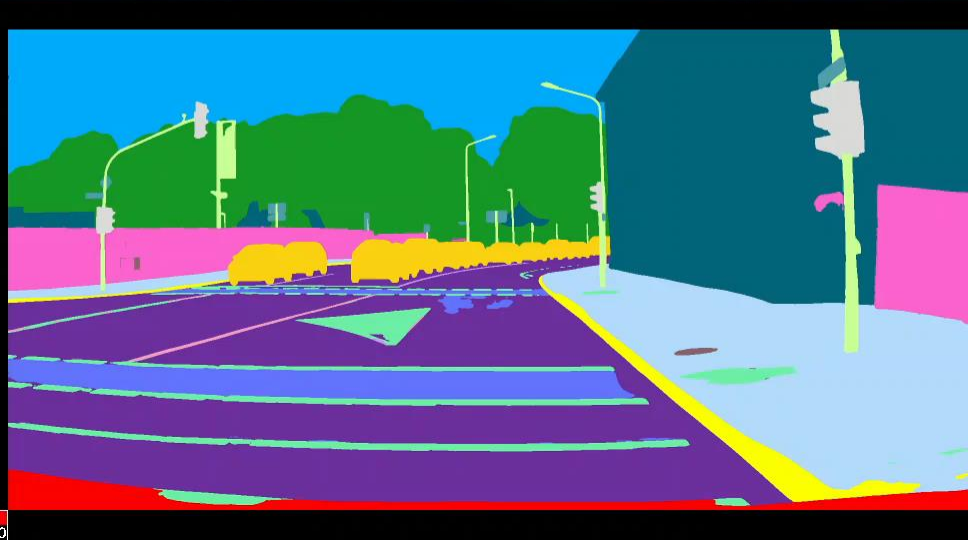
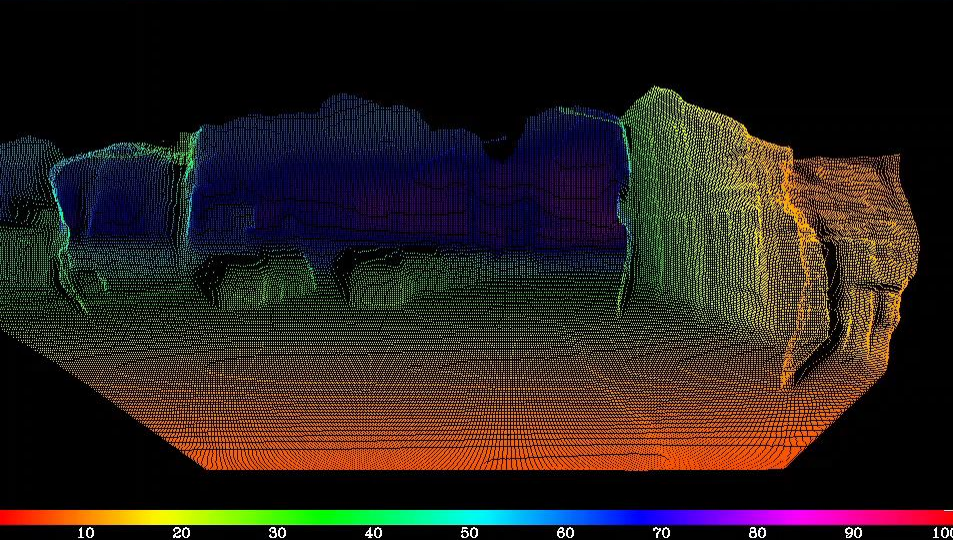
Proposed Development Process

Proposed Development Process

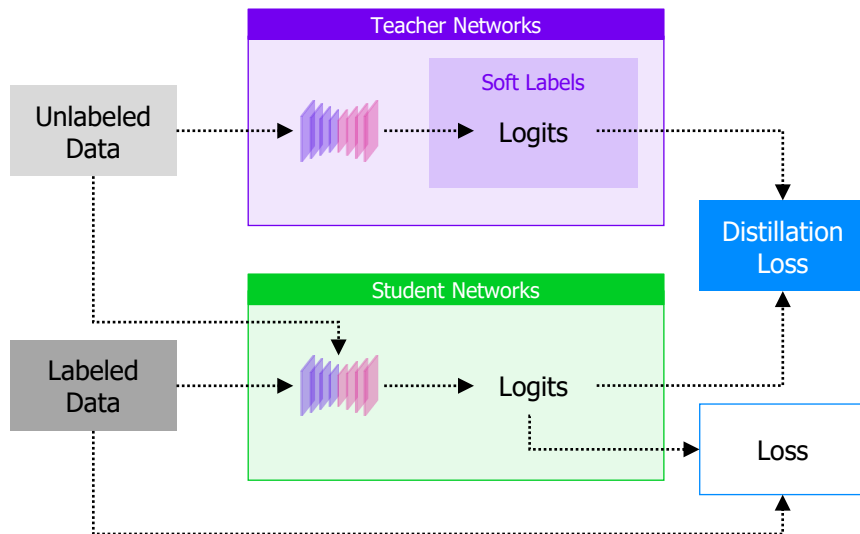
Multiple Teacher - Unified Student learning

Fixed during training
Updated during training



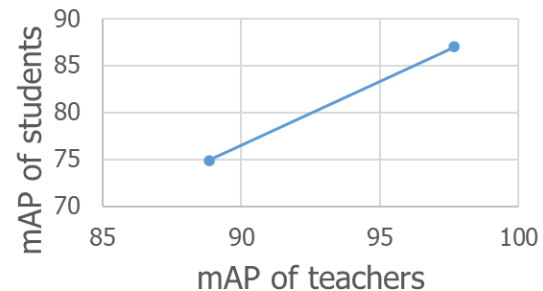


Semi-supervised learning



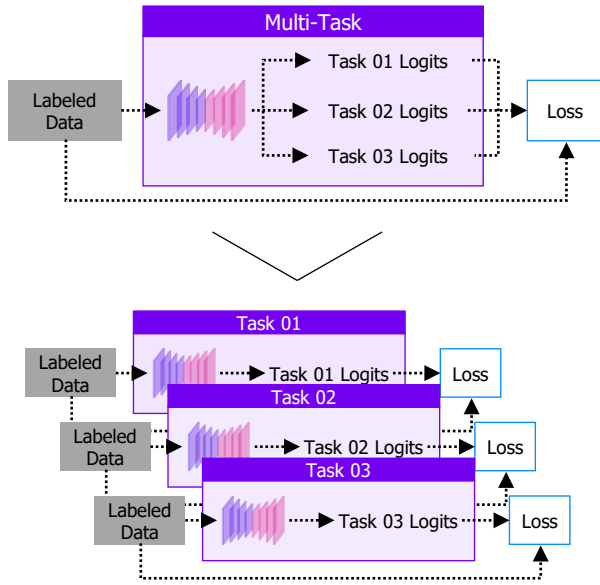
Better teachers, better students.

T-S Learning in Object Detection

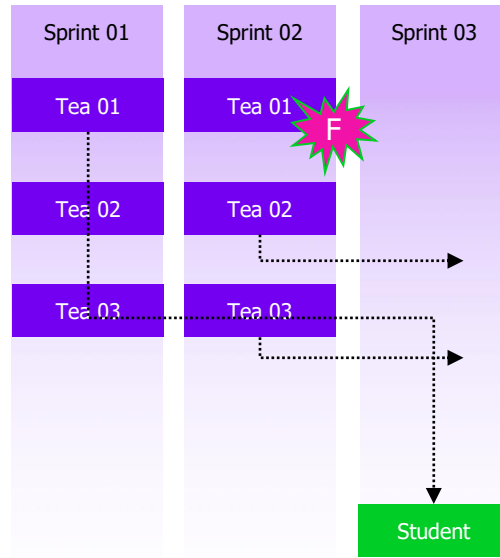


Decoupling Dependencies

Between Tasks

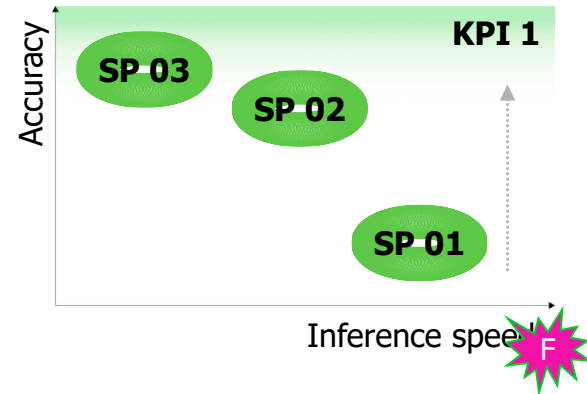


Between Sprints



Between KPIs

For teacher networks,
focus on improving accuracy only.



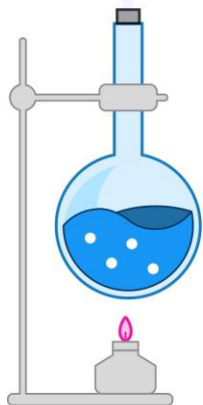
Benefits of Using Teacher-Student Learning

Teacher network

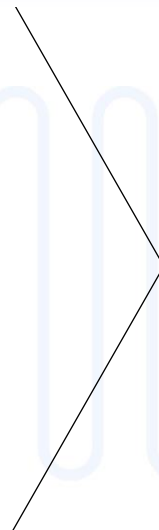
- Can develop **independently** of other networks.
- Focus solely on improving **accuracy**.
- Keep only the **most accurate** models.
- **Not dependent** on target hardware.
- Can **reuse** for other projects.
- Can use **off-the-shelf** DNNs for the initial phase.

Student network

- Use **large-scale unlabeled** datasets.
- Can use **partially labeled** datasets.
- Improve accuracy **for free** with more accurate teacher networks.

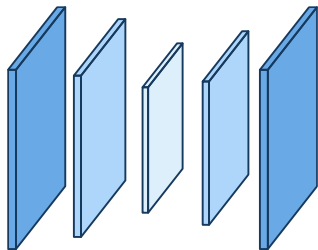


1. Feed *more data* into *deeper and wider* models.
2. Apply *pre-training* if needed.
3. Apply *data augmentation* if needed.



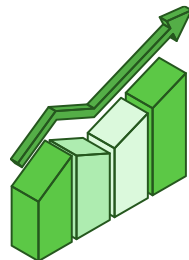
To improve
accuracy





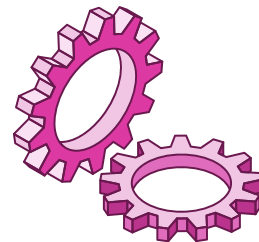
To meet KPIs for inference speed

1. **Design** your network.
2. **Measure** its inference speed **before you start training**.
3. **Start training** once the speed KPI is met.



To improve accuracy

1. Use **more accurate** teacher networks.
2. Use **better losses**, leveraging **cross-task** relationships.



To accelerate training

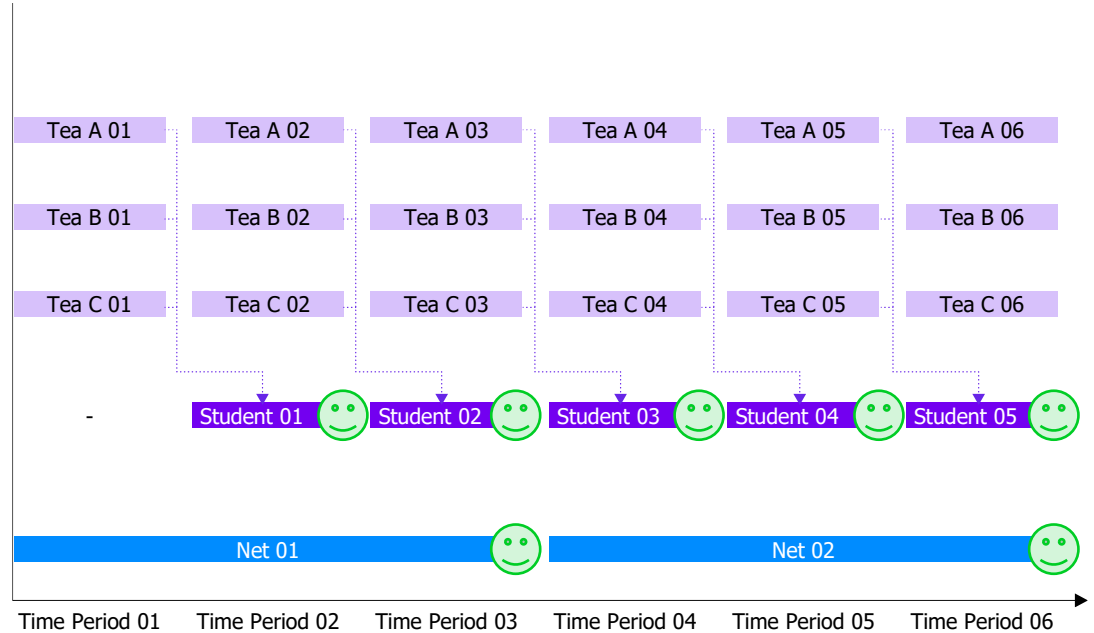
1. **Precompute** and store **soft labels** to SSD.
2. **Load** the labels from SSD during training.

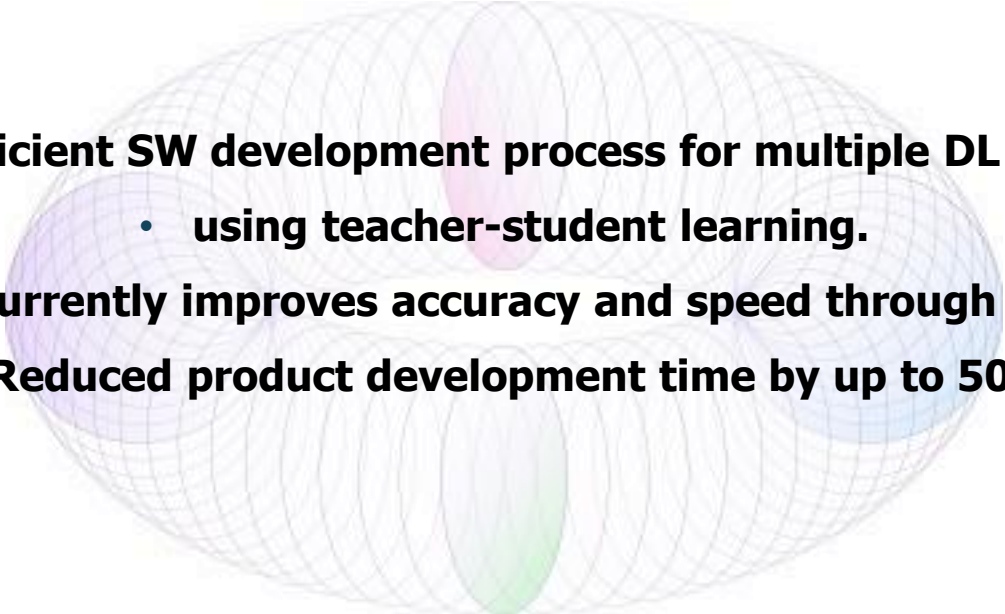
Benefits of The Proposed Process

Rapid prototyping & Continuous updating

Model Release

Network Type	Target HW	KPIs	Task
Pipelined w/T-S learning			
Teacher	Cloud	Accuracy	A
			B
			C
Student	Embedded	Speed Accuracy	A,B,C
Non-pipelined w/o T-S learning			
-	Embedded	Speed Accuracy	A,B,C



- 
- **Efficient SW development process for multiple DL tasks**
 - **using teacher-student learning.**
 - **Concurrently improves accuracy and speed through sprints.**
 - **Reduced product development time by up to 50%.**



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Linked In

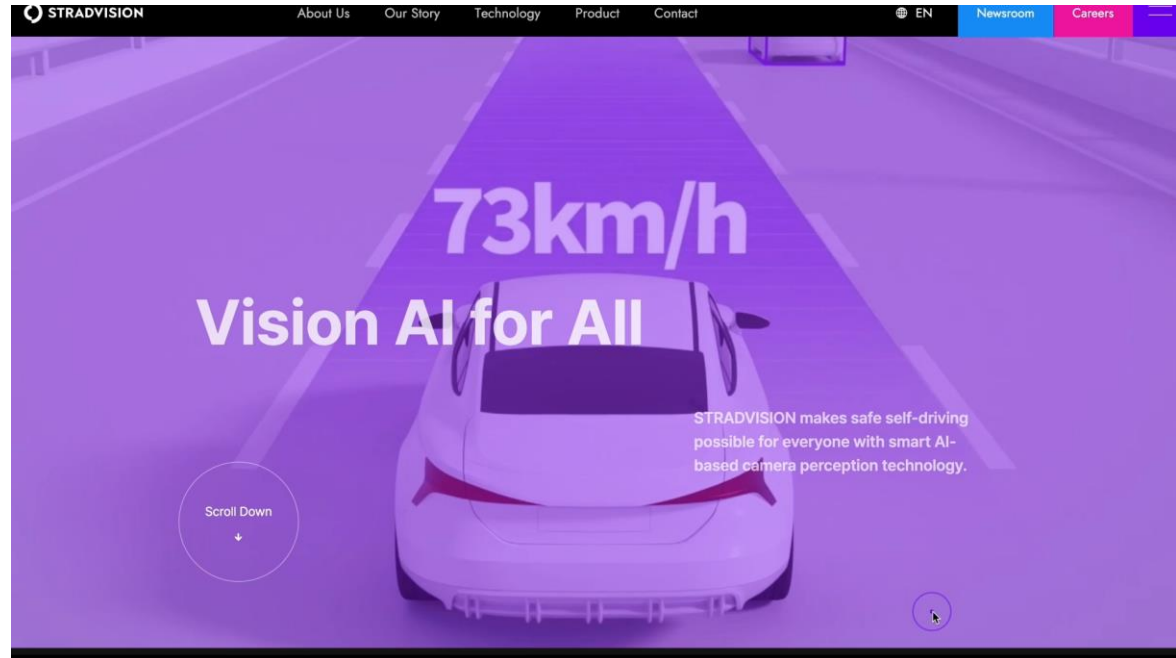
 @stradvision

Youtube

 @stradvision

Webpage

<https://stradvision.com>



- [1] Hinton, Geoffrey, Oriol Vinyals, and Jeff Dean. "Distilling the knowledge in a neural network." *arXiv preprint*, 2015. <https://arxiv.org/abs/1503.02531>
- [2] Gou, Jianping, et al. "Knowledge distillation: A survey." *IJCV*, 2021. <https://arxiv.org/abs/2006.05525>
- [3] Wang, Lin, and Kuk-Jin Yoon. "Knowledge distillation and student-teacher learning for visual intelligence: A review and new outlooks." *IEEE TPAMI*, 2021. <https://arxiv.org/abs/2004.05937>