2023 embedded VISION SUMMIT

How Transformers Are Changing the Nature of Deep Learning Models

Tom Michiels Principal System Architect Synopsys

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- The surprising rise of transformers in vision
- The structure of attention and transformer
- Transformers applied to vision
- Why transformers are here to stay for vision

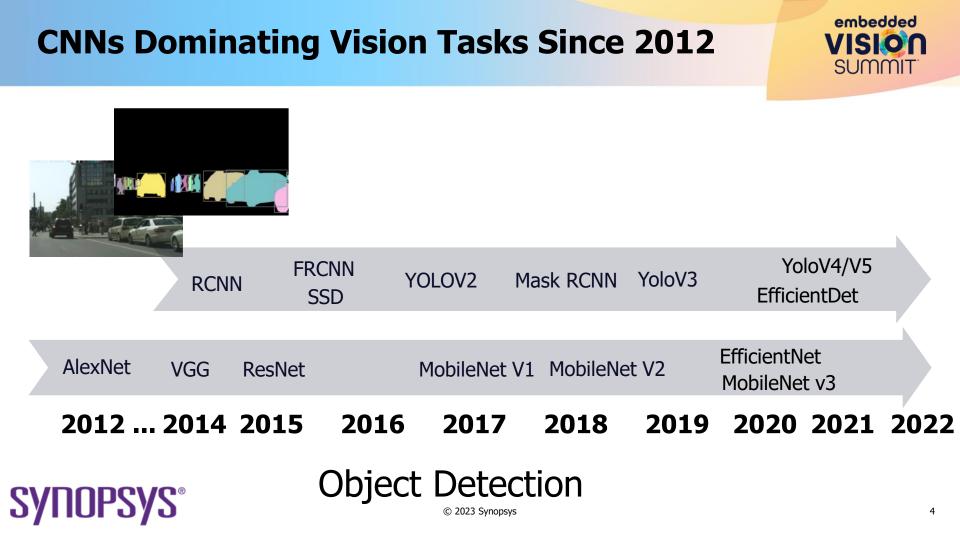


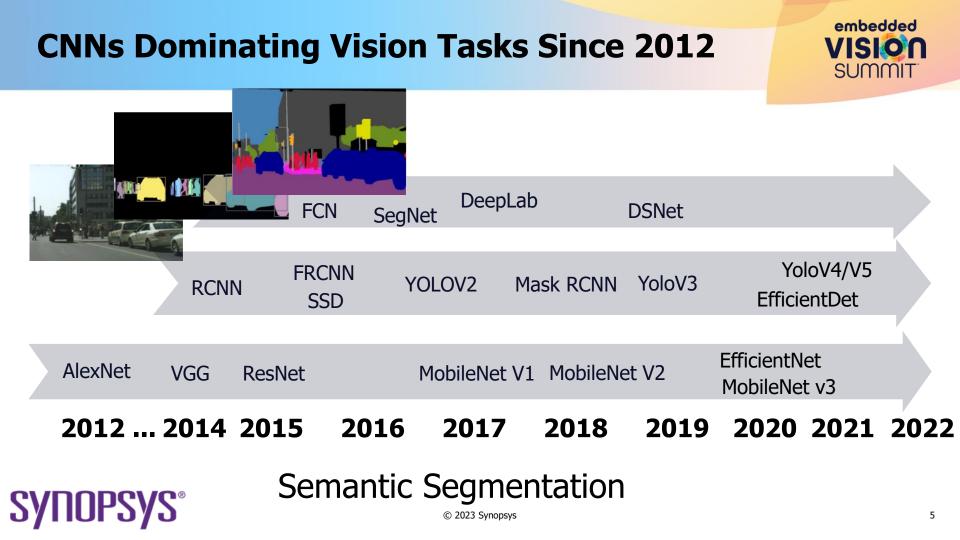
CNNs Dominating Vision Tasks Since 2012

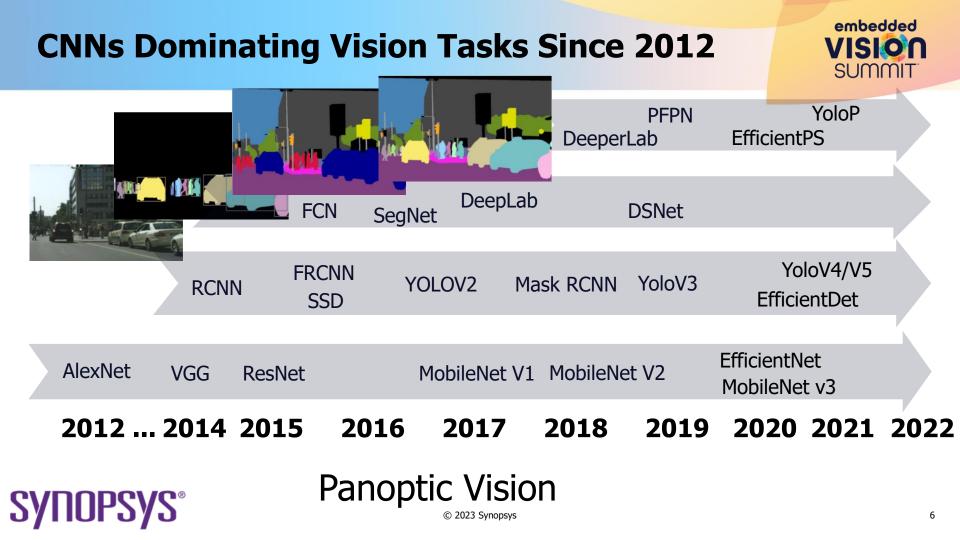






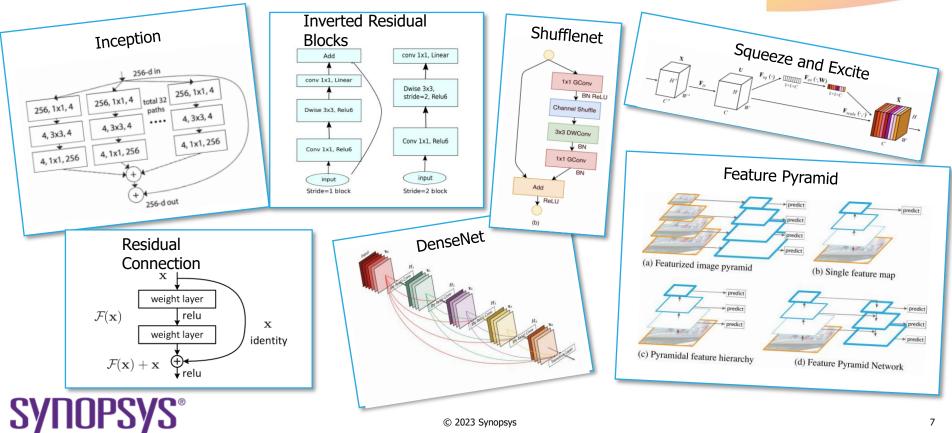






A Decade of CNN Development...



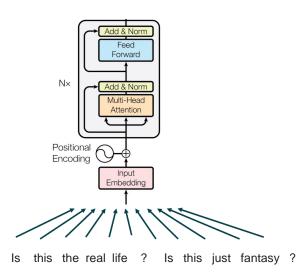


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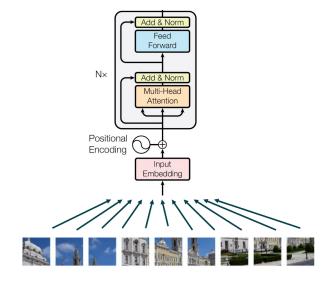
Beaten in Accuracy by Transformers



Transformer, a model designed for natural language processing



... without any modifications applied to image patches, beats the highly specialized CNNs in accuracy

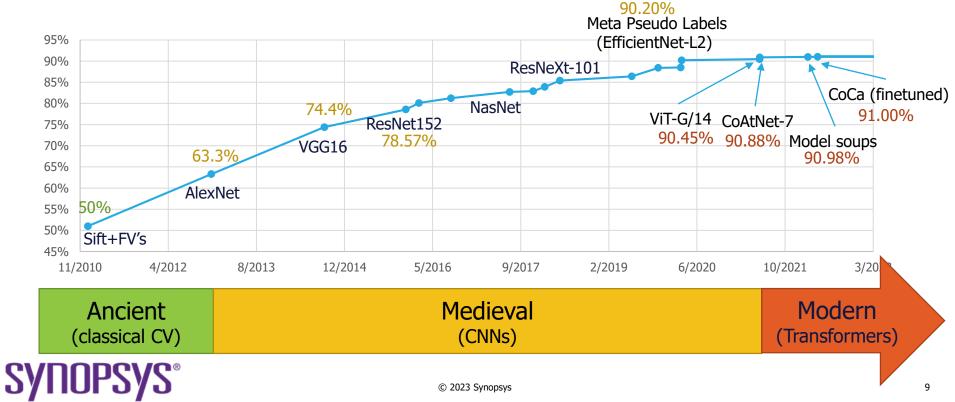


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Accuracy Records on ImageNet



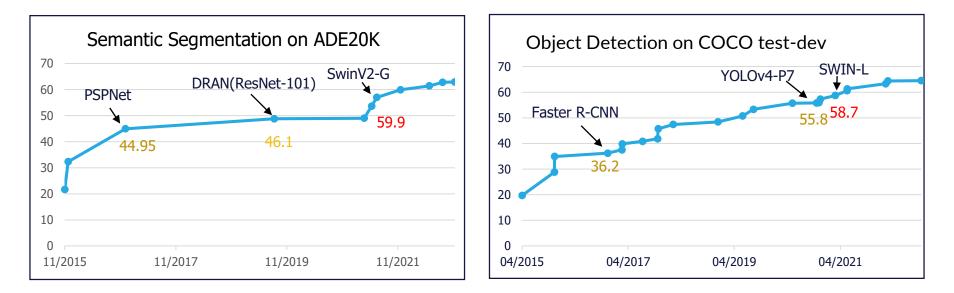
State-of-the-art Top-1 Accuracy ImageNet, entering a new era?



Transformers in Other Vision Tasks

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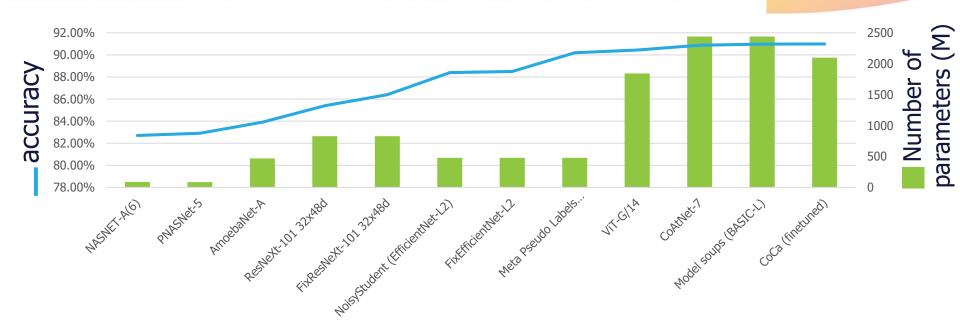




State-of-the-Art of other Vision tasks are dominated by transformers

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But These State-of-the-Art Models Are Huge!



Is the state-of-the-art really relevant for embedded applications?

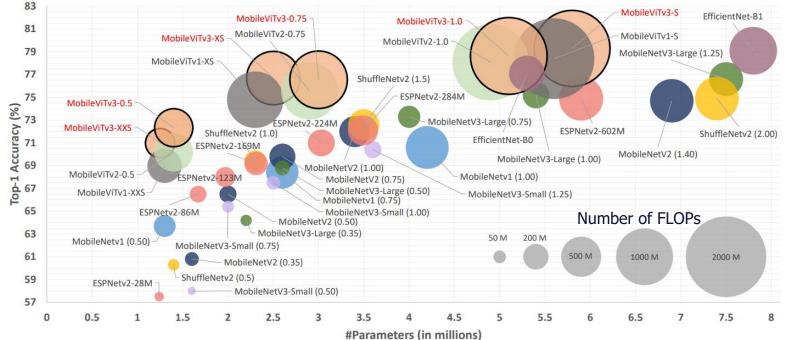
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Compact Transformers versus CNNs





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source MobileViTv3 https://arxiv.org/abs/2209.15159

Mobile ViT: Small Mobile (Paper by Apple, March 2022)



https://arxiv.org/pdf/2110.02178.pdf

Model	# Params 🎚	FLOPs 🎚	Top-1 ↑	Inference Time (ms)		
	· · · · · · · · · · · · · · · · · · ·	· · · · · · ·	-	iPhone12 - CPU	iPhone12 - Neural Engine	
MobileNetv2 DeIT PiT MobileViT (Ours)	3.5 M 5.7 M 4.9 M 2.3 M	0.3 G 1.3 G 0.7 G 0.7 G	73.3 72.2 73.0 74.8	7.50 ms 28.15 ms 24.03 ms 17.86 ms	0.92 ms 10.99 ms 10.56 ms 7.28 ms	CPU/NNE = 8.1X CPU/NNE = 2.5X
	0.7X Model Size	2.3X FLOPs A	+1.5% ccuracy	2.4X Time	7.9X Time	

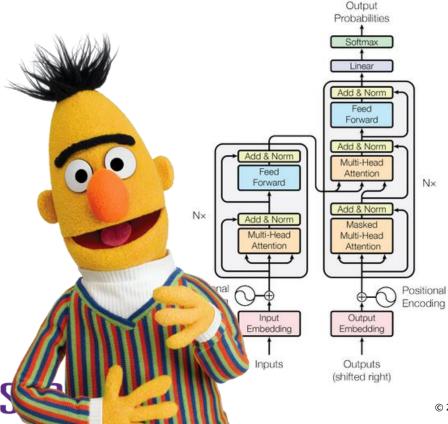
- Observations in paper
 - On embedded devices (iPhone) MobileViT is slower than CNN based methods
 - Because the AI accelerator on iPhone is not as optimized for transformers as it is for CNNs
 - The authors expect that future AI accelerators will better support transformers

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The Structure of Attention and Transformer

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Bert and Transformers





- Attention is all you need!(*)
- Bidirectional Encoder Representations from
 Transformers
- A transformer is a deep learning model that uses attention mechanism
- Transformers were primarily used for natural language processing
 - Translation
 - Question answering
 - Conversational AI
- Successful training of huge transformers
 - MTM, GPT-3, T5, ALBERT, RoBERTa, T5, Switch
- Transformers are successfully applied in other application domains with promising results for embedded use

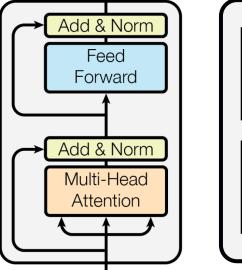
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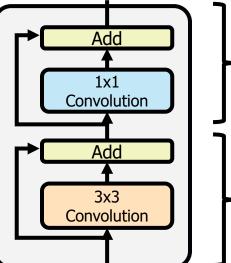
Convolutions, Feed Forward, and Multi-Head Attention



Transformer





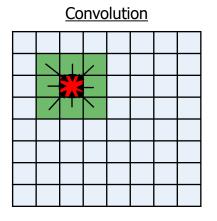


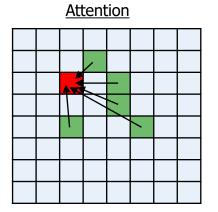
- The feed forward layer of the transformer is identical to a 1x1 convolution
- In this part of the model, no information is flowing between tokens/pixels
- Multi-head attention and 3x3 convolution layers are the layers responsible for mixing information between tokens/pixels

Convolutions as Hard-Coded Attention

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Both Convolution and Attention Networks mix in features of other tokens/pixels

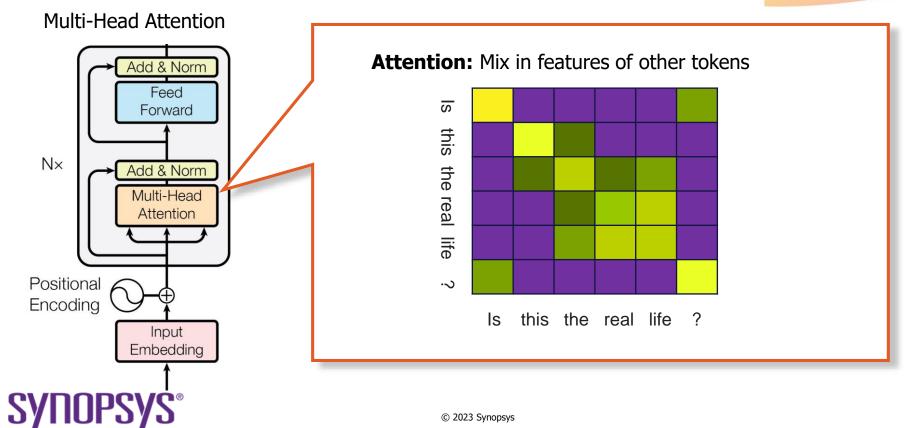




Convolutions mix in features from tokens based on fixed spatial location Attention mix in features from tokens based on learned attention



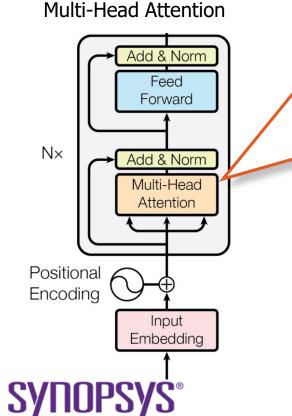
The Structure of a Transformer: Attention

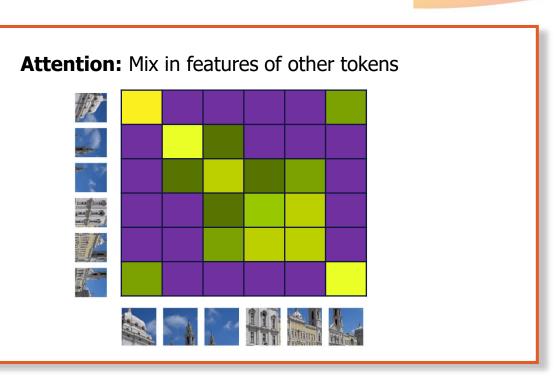


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The Structure of a Transformer: Attention



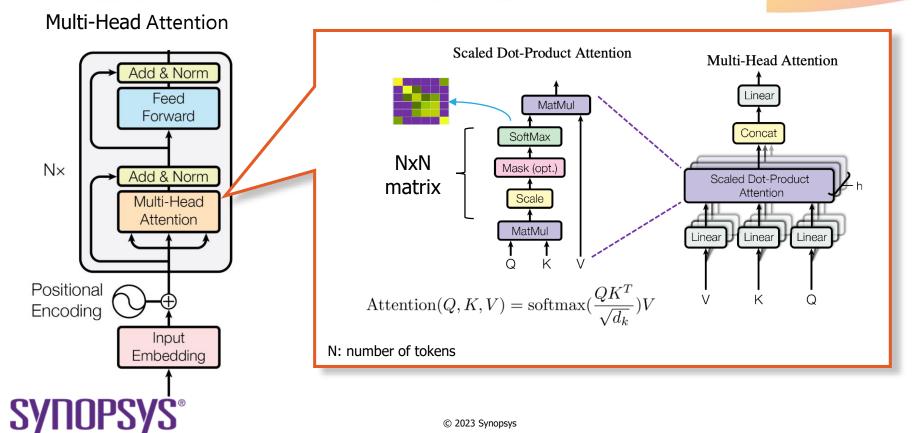


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The Structure of a Transformer: Attention

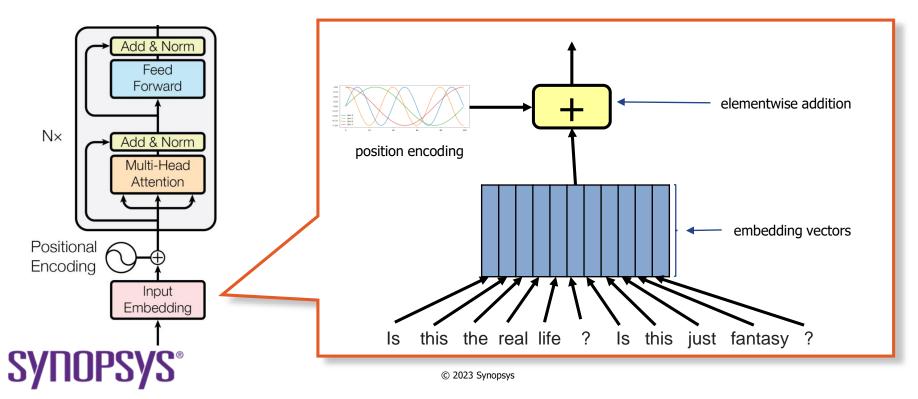


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The Structure of a Transformer: Embedding

Embedding of input tokens and the positional encoding



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Applying Transformers to Vision Tasks

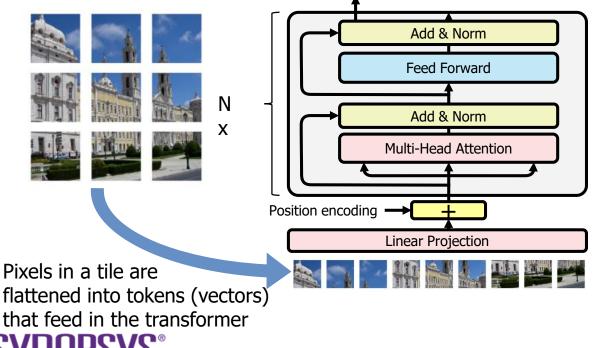


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Vision Transformers (ViT/L16 or ViT-G/14)

An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale(*)

Image is split into tiles



Vision transformers are **bestknown method for image classification**

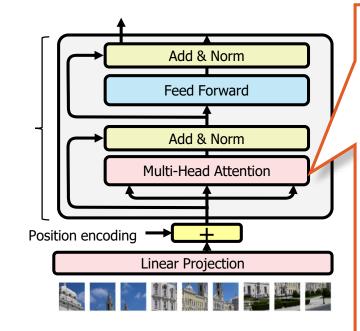
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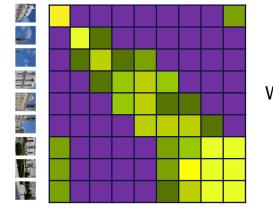
They are beating convolutional neural networks in **accuracy** and **training time**, but **not in inference time**

(*) https://arxiv.org/abs/2010.11929

Vision Transformer → Increasing Resolution



Attention matrix scales quadratically with the number of patches



N x N matrix Where N = the number of tokens/patches

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Swin Transformers



Stage 3

Swin

Block

 $\times 6$

16×

 $\frac{H}{8} \times \frac{W}{8} \times 2C$

Hierarchical Vision Transformer Using Shifted Windows (*)

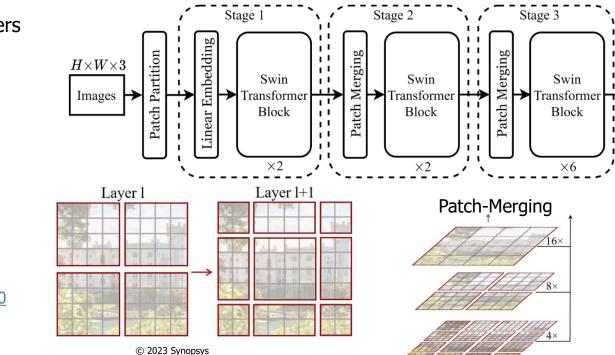
Adaptation makes transformers scale for larger images:

- 1. Shifted window attention
- 2. Patch-merging

State of the art for

- Object detection (COCO) •
- Semantic segmentation • (ADE20K)

(*) <u>https://arxiv.org/abs/2103.14030</u>



 $\frac{H}{4} \times \frac{W}{4} \times C$

 $\frac{H}{4} \times \frac{W}{4} \times 48$

Action Classification with Transformers

Video Swin Transformer $\frac{T}{2} \times \frac{H}{4} \times \frac{W}{4} \times 96$ $\frac{T}{2} \times \frac{H}{4} \times \frac{W}{4} \times C$ $\frac{T}{2} \times \frac{H}{8} \times \frac{W}{8} \times 2C \qquad \qquad \frac{T}{2} \times \frac{H}{16} \times \frac{W}{16} \times 4C \qquad \frac{T}{2} \times \frac{H}{32} \times \frac{W}{32} \times 8C$ MLP MLP Stage 4 Stage 2 Stage 3 `\. / Stage 1 . Τ. LN Embedding **3DPatch Partitio** 1.1 Merging Merging Merging $T \times H \times W \times 3$ 11 Video Swin Video Swin Video Swin Video Swin 11 Transformer → Transformer → Transformer Videos Transformer Patch Patch 1.1 Patch 3D W-MSA 3D SW-MSA Block Block Block Block 11 Linear 1 1 1.1 11 . 1.1 1.1 11 1 1 11 LN 11 1 1 $\times 2$ 1 \ $\times 2$ $\times 6$ \mathbf{z}^{l-1} $\times 2$ 1 1 Video Swin Transformers extend the (shifted) 3D local window to perform self-attention window to three dimensions (2D spatial + time) A token Today's state of the art on Kinetics-400 and Kinetics-600 Layer 1+1 Laver 1 3D tokens: T'×H'×W' = $8 \times 8 \times 8$ # window: $2 \times 2 \times 2 = 8$ # window: $3 \times 3 \times 3 = 27$ Window size: $P \times M \times M = 4 \times 4 \times 4$

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LN

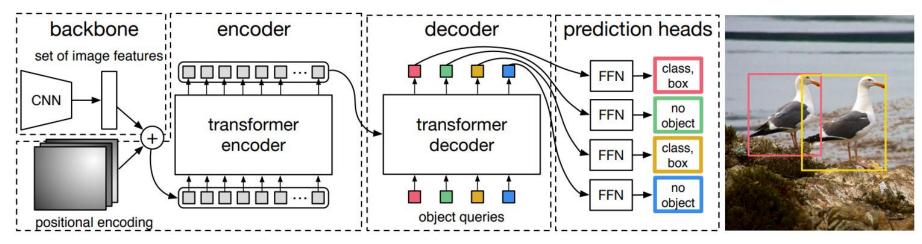
LN

https://arxiv.org/abs/2106.13230

Object Detection with Transformers



End-to-End Object Detection with Transformers (Facebook 2020)



DETR uses a CNN (ResNet-50) as a backbone Off-the-shelf transformer encoder and decoder Trained Object Queries retrieve possible candidates for objects

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Training Vision Transformers

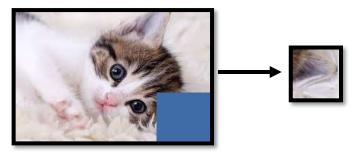


- **More data** required to train a transformer to overcome the lack of inductive bias of convolution
- Vision Transformers take **significantly less training time** than comparable CNN's
- Self-supervised Pre-Training for Vision Transformers

→"cat"



Supervised learning



Self-Supervised learning

Why Attention and Transformers are Here to Stay for Vision



Inductive Bias of CNNs

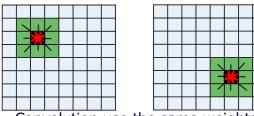


Recognizing Cat Fur



Recognizing a whole Cat



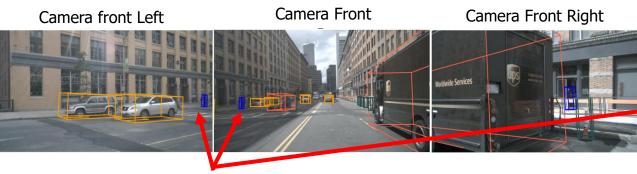


Convolution use the same weights for processing every pixel

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The inductive bias of a convolution, is more helpful for recognizing low level features like cat fur than for recognizing more complex objects like cats

Inductive Bias of CNNs and Sensor Fusion



Fused in a single object

- Many real-life applications use multiple sensors
- Transformers excel in sensor fusion
- The inductive bias of CNNs designed for grid-like structures limits their effectiveness in sensor fusion

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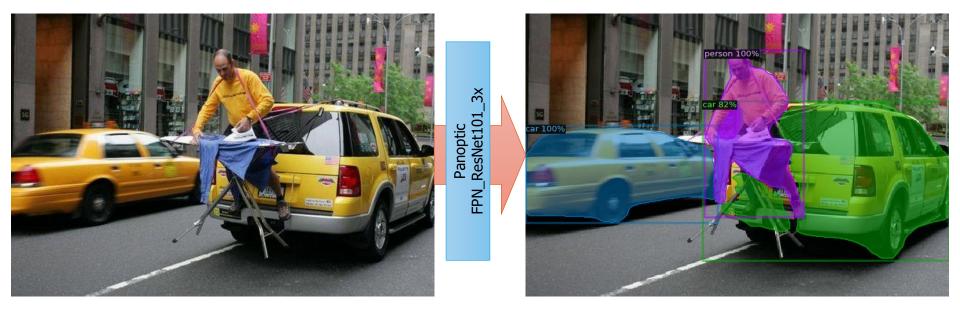


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Panoptic Segmentation Using CNNs





Panoptic Segmentation combines predictions from both instance and semantic segmentation in a unified output

Image source: https://www.barnorama.com/wp-content/uploads/2016/12/03-Confusing-Pictures.jpg **SYNOPSYS**[®] Model Used: Detectron2 - COCO-PanopticSegmentation/panoptic fpn R 101 3x

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Multimodal Transformers





LLaVA Language and

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User: What is unusual about this image?

LLaVA: The unusual aspect of the image is that a man is ironing clothes on the back of a yellow minivan while it is on the road. This is an unconventional and unsafe place to perform such an activity, as ironing clothes typically requires a stable surface and appropriate equipment. Ironing clothes in a moving vehicle could lead to potential hazards for both the person doing the ironing and other road users.

https://arxiv.org/pdf/2304.08485.pdf

How Much Intelligence Do We Need?





Panoptic Segmentation

User: What is unusual about this image?

LLaVA: The unusual aspect of the image is that a man is ironing clothes on the back of a yellow minivan while it is on the road. This is an unconventional and unsafe place to perform such an activity, as ironing clothes typically requires a stable surface and appropriate equipment.

Multi-modal language/vision

How much (artificial) intelligence is required for real-life applications?

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Why Transformers Are Here to Stay in Vision



- Attention-based networks outperform CNN-only networks on accuracy
 - Highest accuracy required for high-end applications
- Models that combine vision transformers with convolutions are more efficient at inference
 - Examples: MobileViT^(*), CoAtNet^(**)

SALIGh2A2

- Real-life vision: demands beyond CNN inductive bias
 - Scene understanding needs common-sense knowledge that may not be learned by vision alone
 - Sensor fusion: complex geometrical mappings are ill-suited for CNN bias

(*) <u>https://arxiv.org/abs/2110.02178</u> (**) <u>https://arxiv.org/abs/2106.04803v2</u>

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- Transformers are deep learning models primarily used in the field of NLP
- Transformers lead to state-of-the-art results in other application domains of deep learning like vision and speech
 - They can be applied to other domains with surprisingly little modifications
 - Models that combine attention and convolutions outperform convolutional neural networks on vision tasks, even for small models
- Transformers and attention for vision applications are here to stay
 - Real world applications require knowledge that is not easily captured with convolutions



Resources



Resources

ARC NPX6 NPU IP

www.synopsys.com/npx

Visit Synopsys Booth 309

- Partner demo: Visionary.ai True Night Vision SW ISP
- Meet with Synopsys executives and experts
 - Discuss emerging neural network architectures like transformers and vision/object detection for safety-critical automotive SoCs
 - Learn about the latest in practical technology to bring visual intelligence into embedded systems, mobile apps, cars, and PCs